



On using modern C++ and nested recursive task parallelism for HPC applications with AllScale

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From Performance Prediction to Compilers and Distributed Computing

- **Superb and Vienna Fortran Compiler** [SFB Aurora; Apart Working Group]

- Parameter based Performance Prediction Tool (P³T) for **HPF**
- Scalea (instrumentation, monitoring, performance analysis) by Hong-Linh Truong (now Aalto University) for **Vienna Fortran**
- Zenturio (automatic experiment generation for large scale analysis) by Radu Prodan (Klagenfurt University) for **Vienna Fortran**

Fortran

- **Askalon (application development and runtime for the Grid and the Cloud)** [8 EU projects]

- performance prediction for scientific workflows (Farrukh Nadeem, King Abdulaziz University)
- performance prediction for services and tasks for clouds (Thanh-Phuong Pham, Helsinki University)
- scheduling and resource management

C, Java,
Python

more Compilers and runtime system

- **Insieme C/C++ compiler** (Allscale EU project)

- Cilk, OpenMP
- auto-tuning for multiple parameters
- runtime optimization
- performance prediction (distance to finish task)

C/C++

- **Allscale API, compiler and runtime system** (Allscale EU project)

- high-level C++ domain specific language
- productivity (hide MPI)
- sophisticated compiler analysis
- recursive task parallelism

C++

- **Celerity API and runtime system for GPU clusters based on SYCL** (FETHPC LIGATE)

- Productivity versus performance
- API research to hide MPI
- focus on asynchronous tasks
- runtime optimization and scheduling

SYCL

more Distributed Systems

- **Apollo (application development and runtime for the edge-cloud continuum)**

- scientific workflows
- programming paradigms, scheduling, resource management
- semi-automatic serverless function generation

YAML,
serverless
functions
C, C++,
Java,
Python, ...

- **Apache Flink**

- data pipelines and big data
- real-time latency intensive stream/batch applications
- targeting edge-cloud
- ensemble scheduling and resource management

Java,
Python,
Scala

Performance models and analysis:

- simple analytical models and real-time measurements
- more complex models based on ML

AllScale – A H2020 Success Story

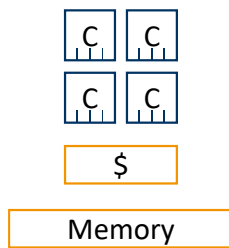
- Horizon 2020 funded project and marked “Success Story”
- Coordinated by Thomas Fahringer, Distributed and Parallel Systems Group and Research Center HPC, Department of Computer Science
- 5 Partners
 - Friedrich-Alexander University Erlangen-Nürnberg
 - IBM Ireland
 - KTH Stockholm
 - Numeca, Brussels
 - Queen’s University Belfast



This project has received funding from the European Union's Horizon 2020 research and innovation programme under grant agreement No. 671603

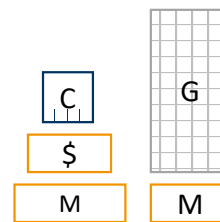
Parallel Architectures

Multicore



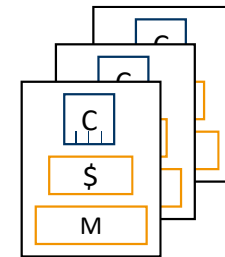
OpenMP/Cilk

Accelerators



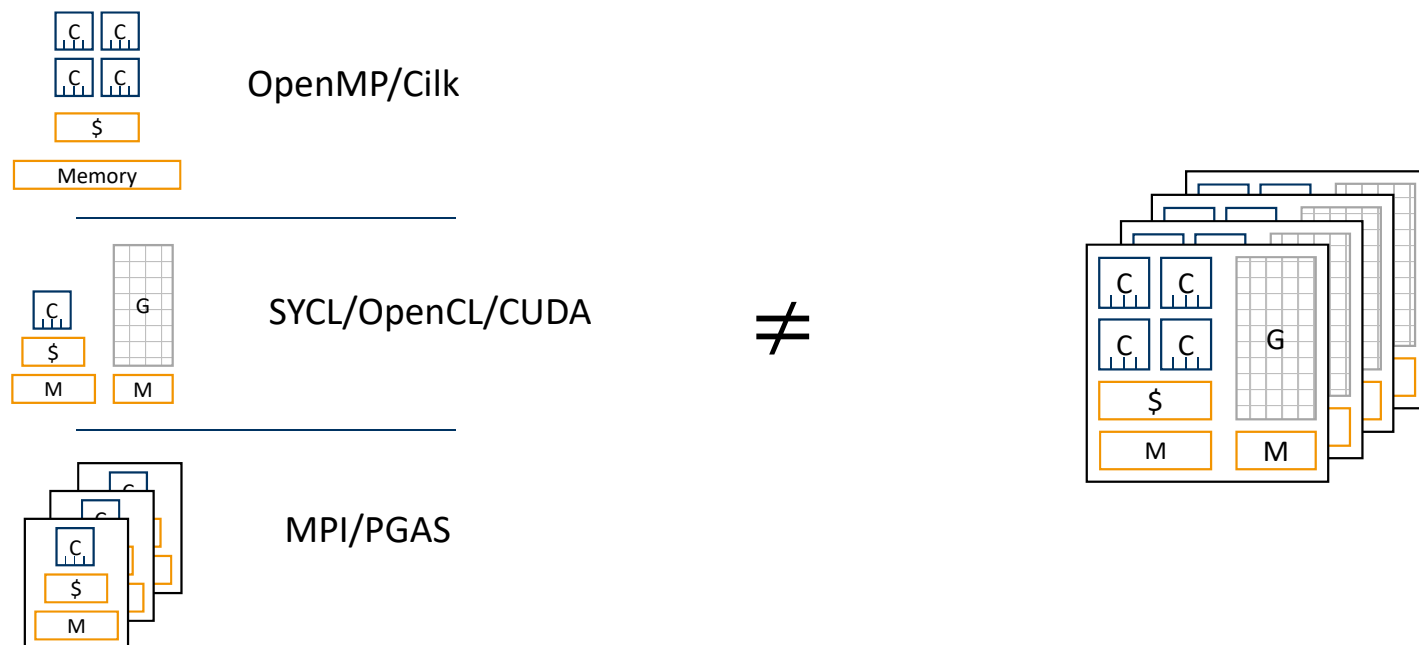
SYCL/OpenCL/CUDA

Clusters



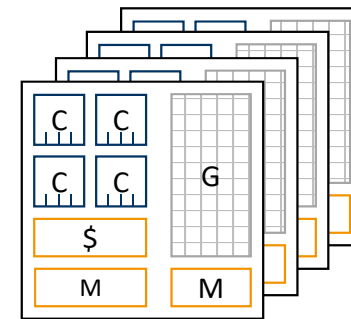
MPI/PGAS

Real World Architectures

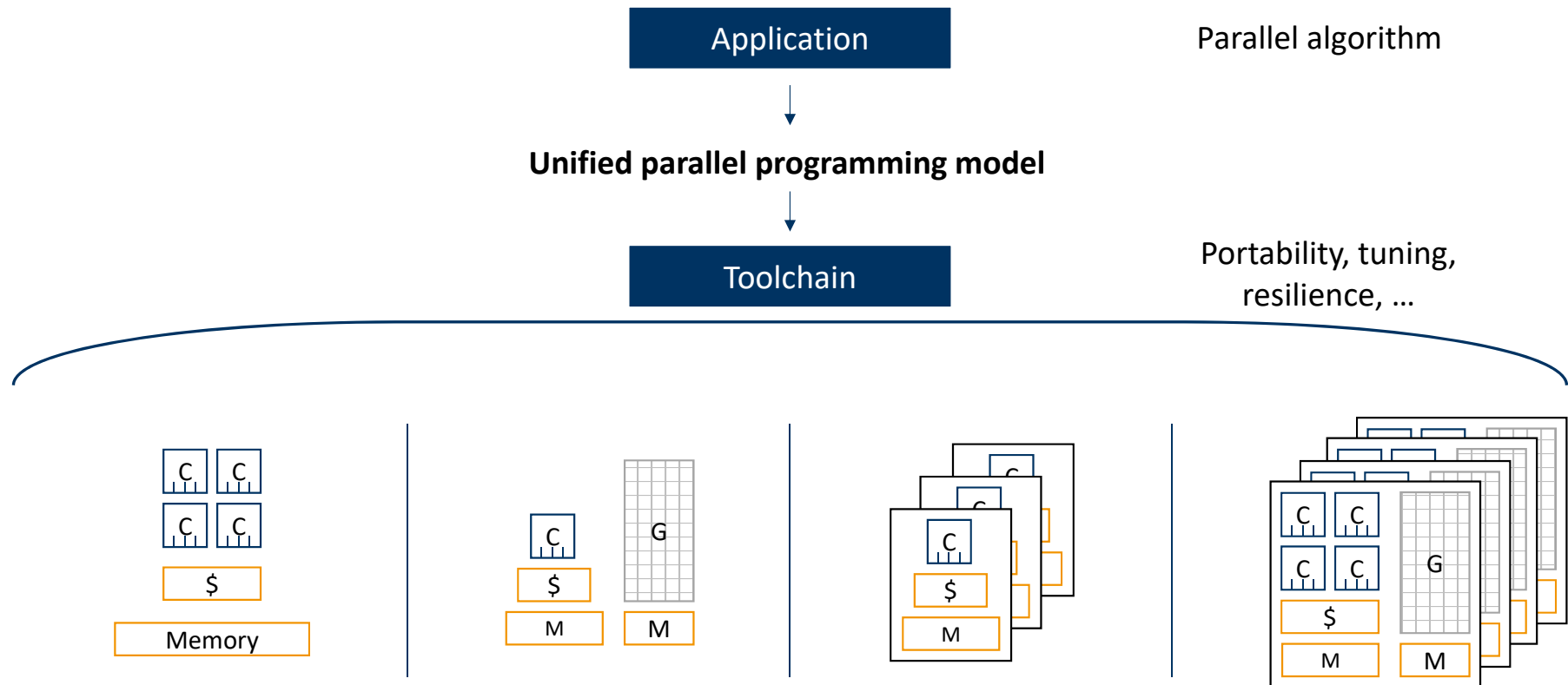


Hybrid Programming Models for Heterogeneous Parallel Architectures

- Issues
 - Hard-coded problem decomposition
 - Lack of coordination among runtime systems
- No built-in support for
 - Portability
 - Auto-tuning
 - Load balancing
 - Monitoring
 - Resilience
 - ...



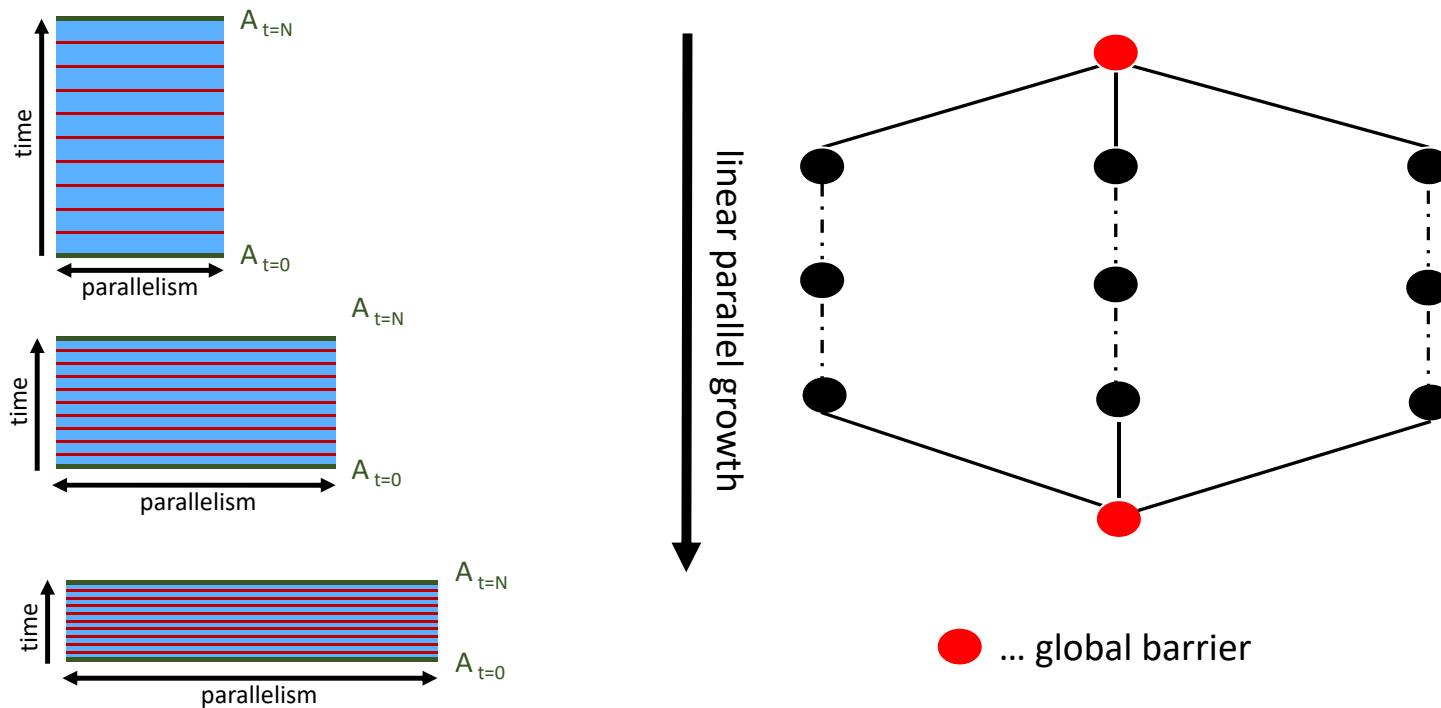
AllScale Vision



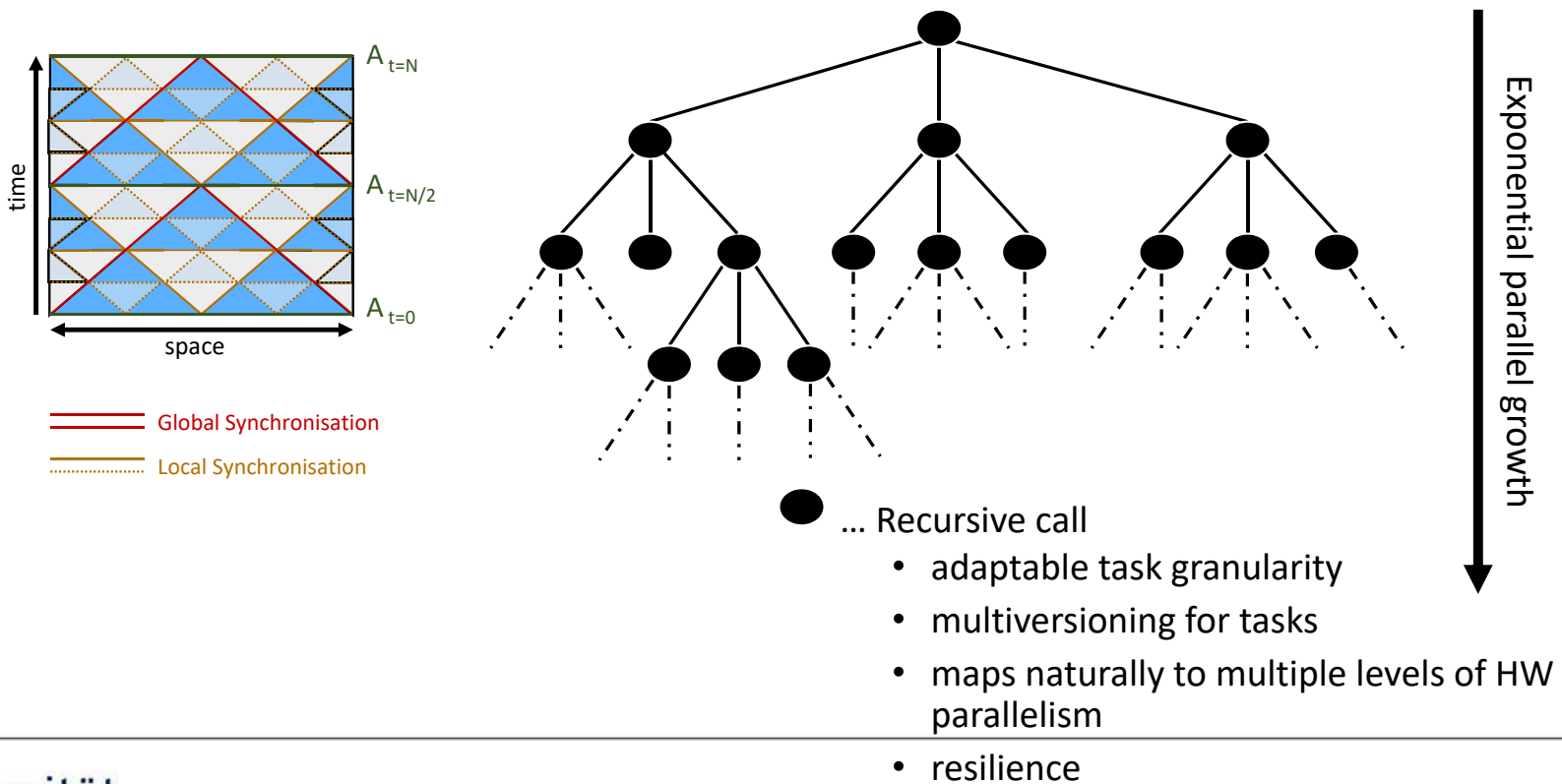
Conventional Flat Parallelism

How to map flat parallelism to a hierarchical parallel architecture?

Complex handling of errors – global operations



Recursive Parallelism

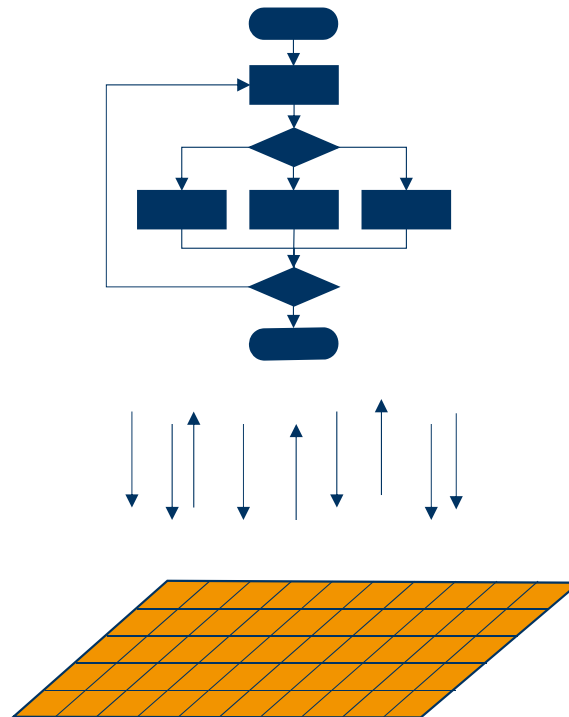


Recursive Task Parallelism Potential

- Branch and bound algorithms
- Place and Route algorithms
- SAT or SMT Solvers, Datalog Engines or similar reasoners
- Combinatorial optimization problems
- Stencil codes, in any number of dimensions
- Dense algebra operations
- N-body simulation
- Rendering

Serial Work and Data

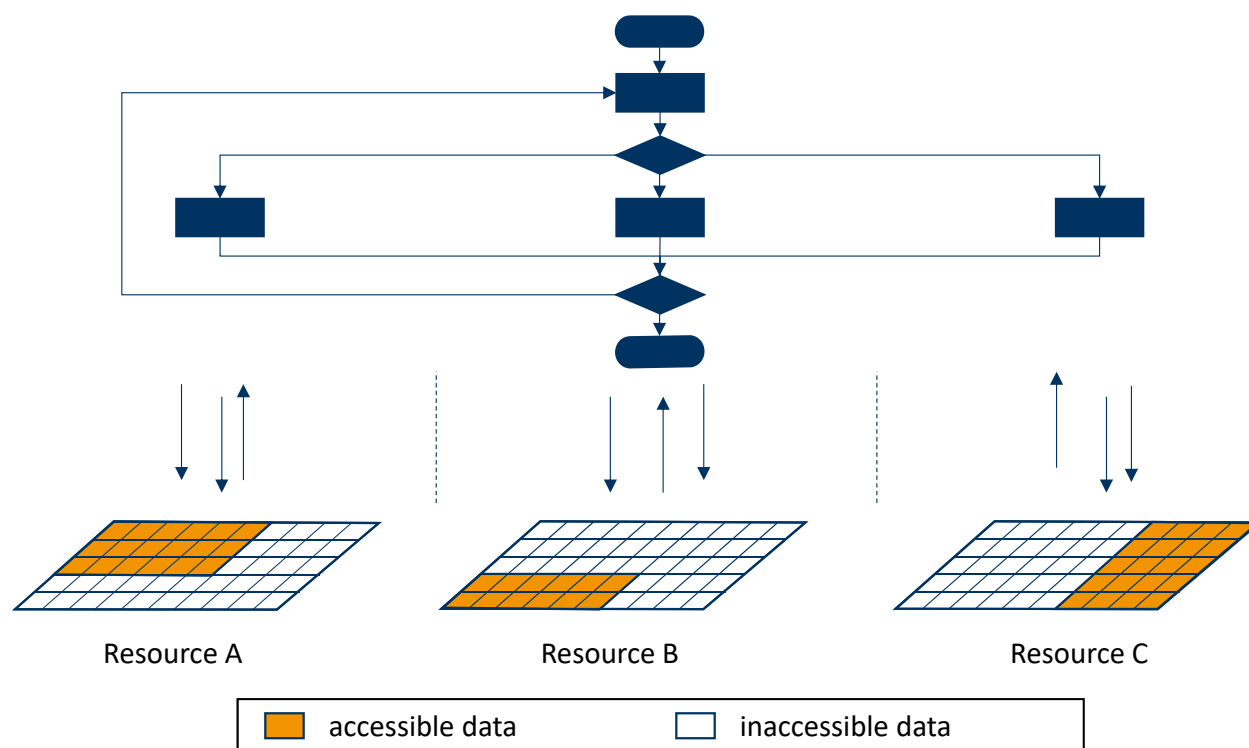
Algorithms
manipulate the
state of
data structures



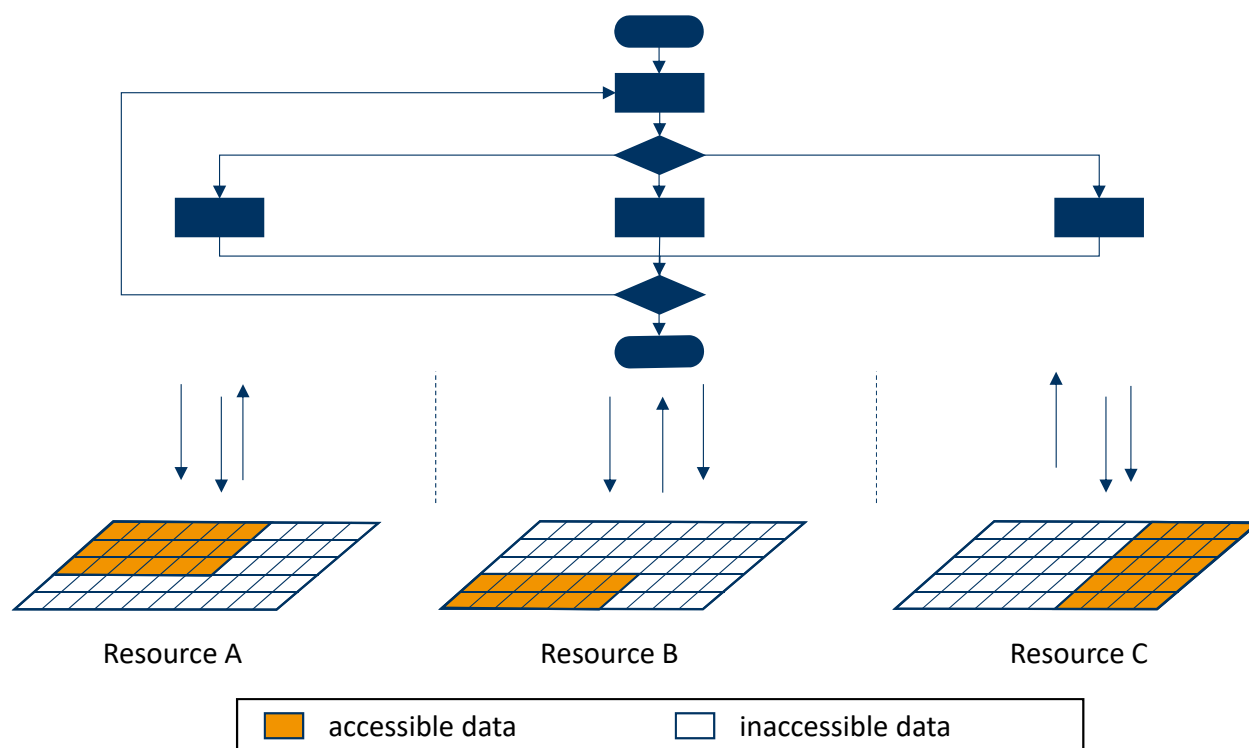
explicitly expressed
in program code

the **implicit** effect
of program code

Parallel Work and Data



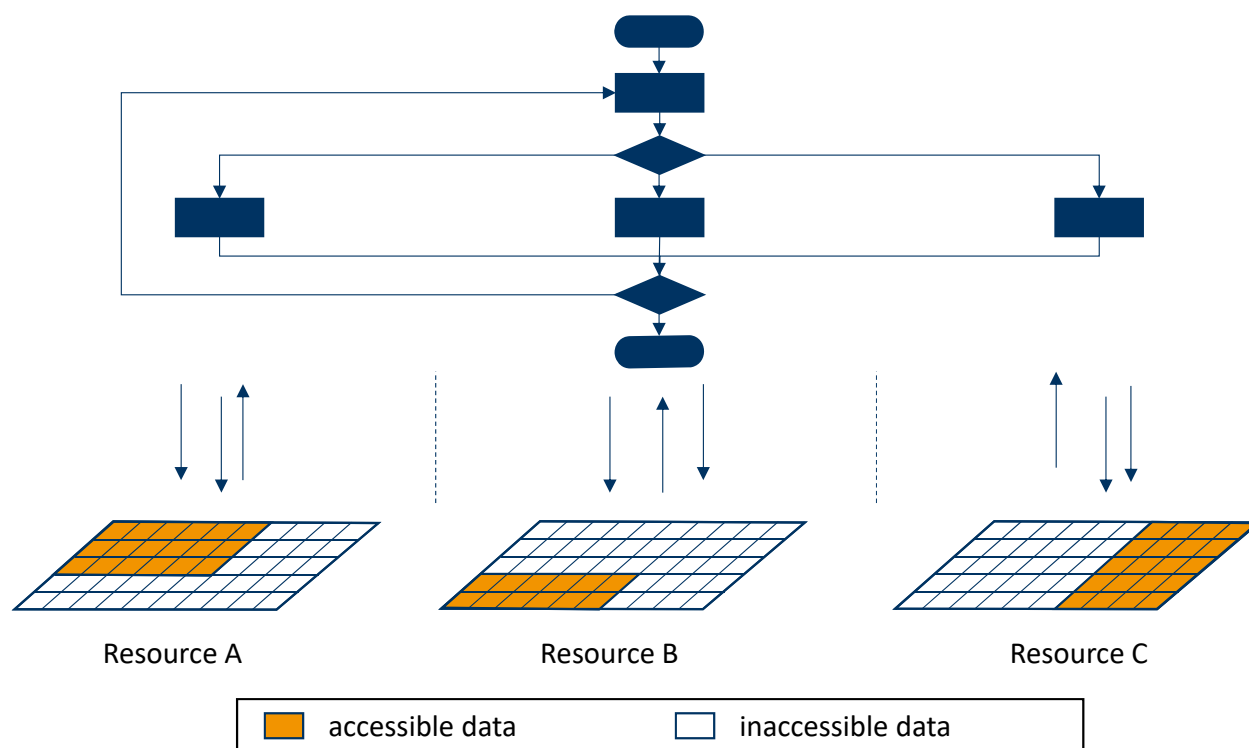
Parallel Work and Data



decomposition of **workload** is main focus of e.g. MPI, OpenMP, Cilk, OpenCL, SYCL, CUDA,...

data structure decomposition and management **left to the user**

Parallel Work and Data



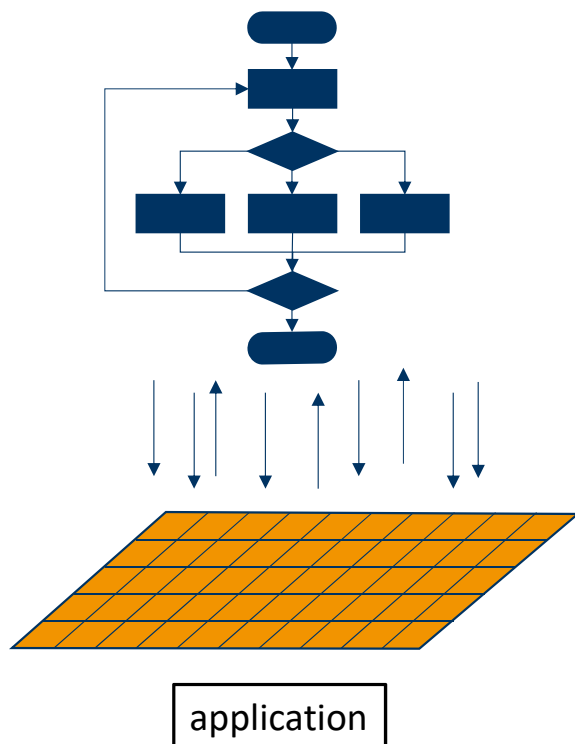
Desired:

advanced system features and services including

- performance **portability**
- inter-node **load balancing**
- **dynamic resource utilization**
- **resilience** to node failures

For those, **runtime systems** require **control** over **distribution of work and data**

AllScale User DSL/API Design



Operators:

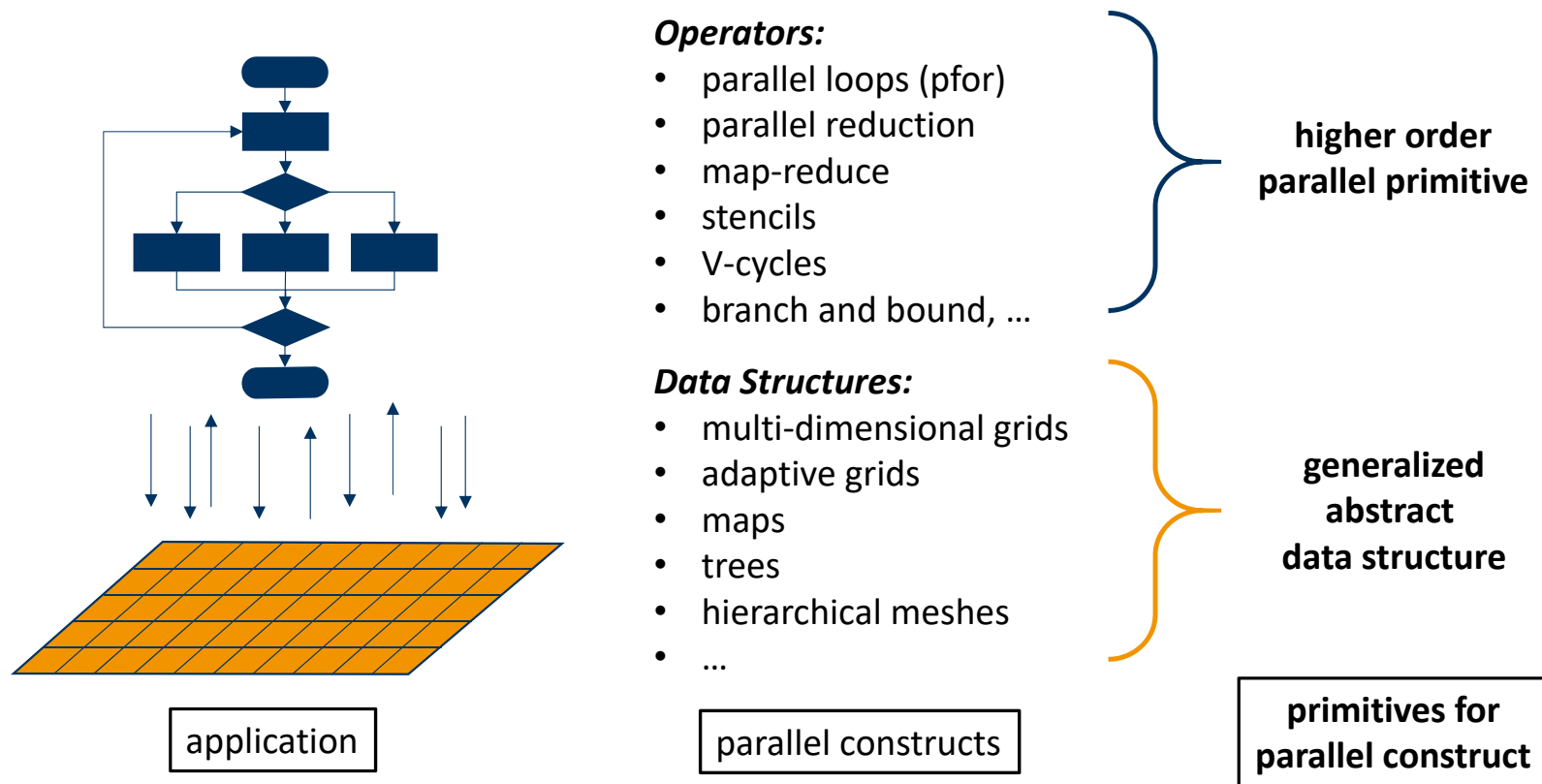
- parallel loops
- parallel reduction
- map-reduce
- stencils
- V-cycles
- brand and bound, linear algebra, ...

Data Structures:

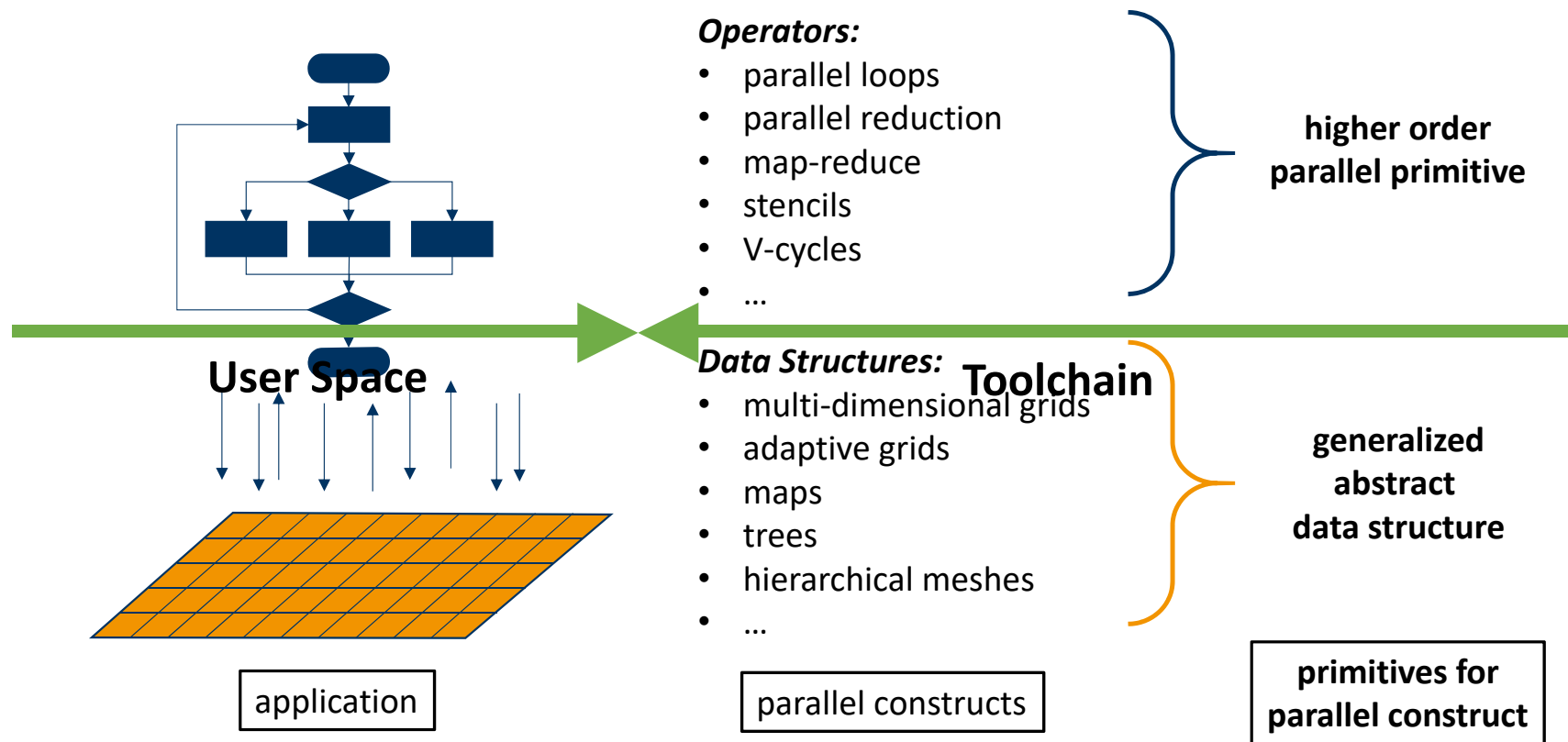
- multi-dimensional grids
- adaptive grids
- maps
- trees
- hierarchical meshes
- ...

parallel constructs

AllScale's Approach

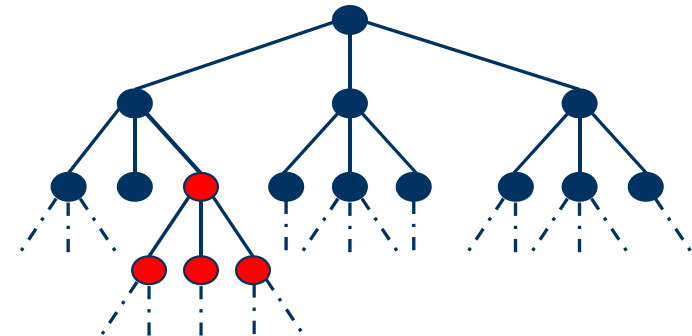
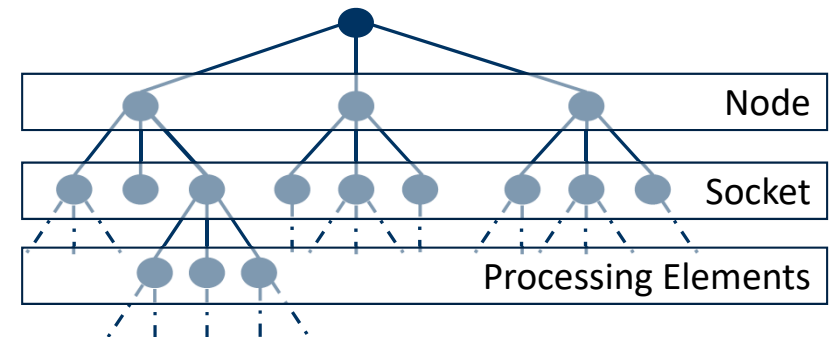
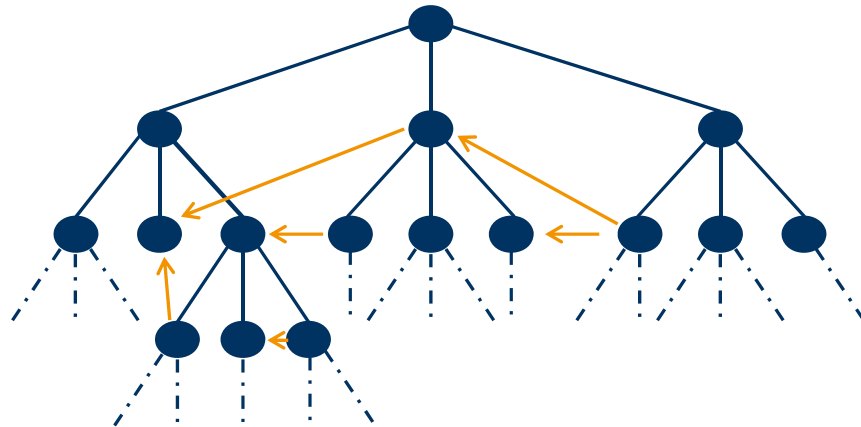


AllScale's Approach



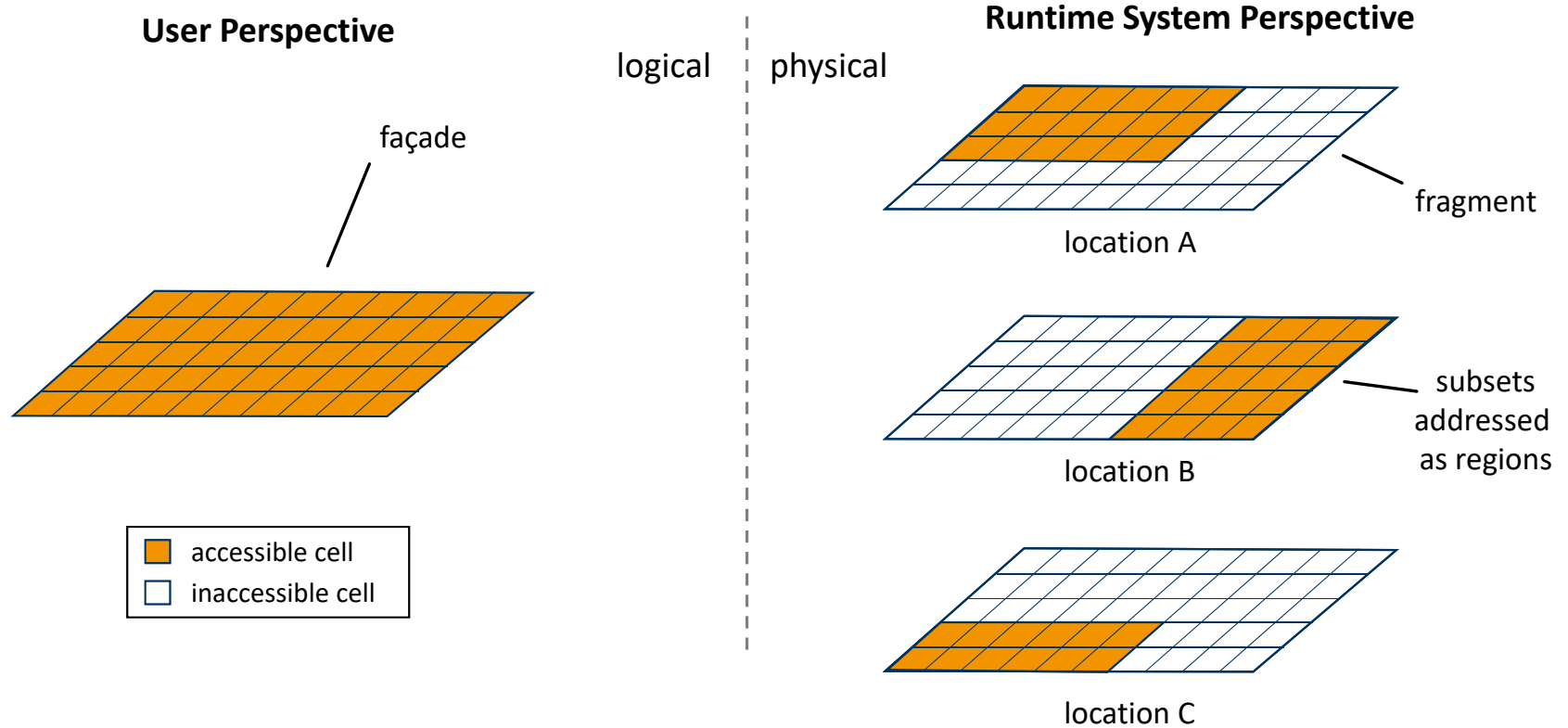
Work Flow Construct (Implicit Task Parallelism): AllScale Core API

- **prec** – a higher order function to
 - express recursive task-based parallelism
 - support fine-grained, hierarchical dependencies

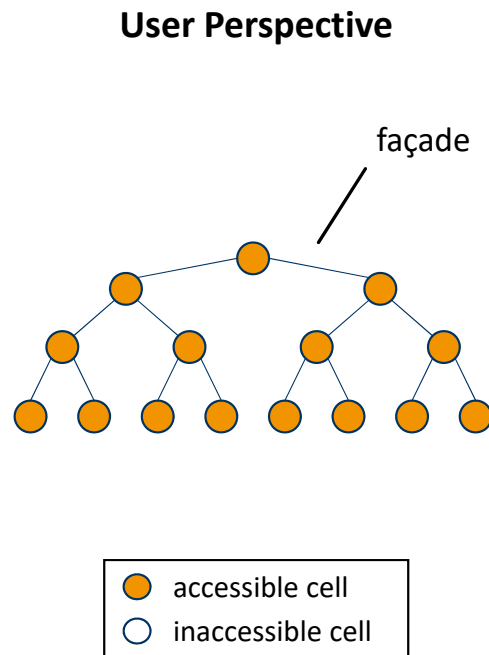


● ... recursive task — ... task hierarchy ← ... fine grained dependencies ● ... failed task

Data Items

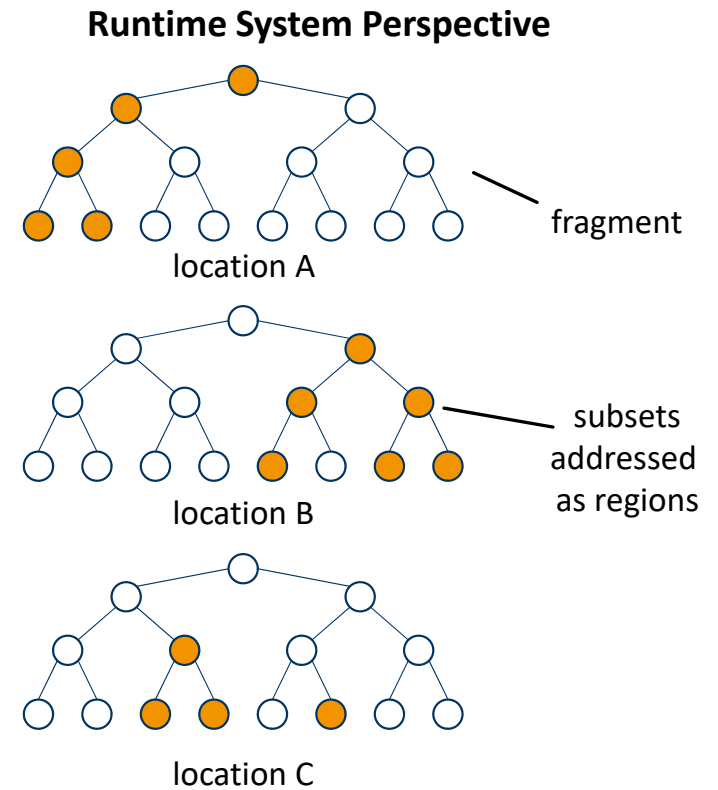


Data Items



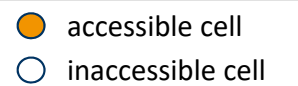
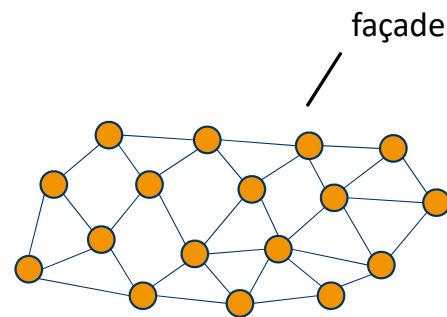
logical

physical



Data Items

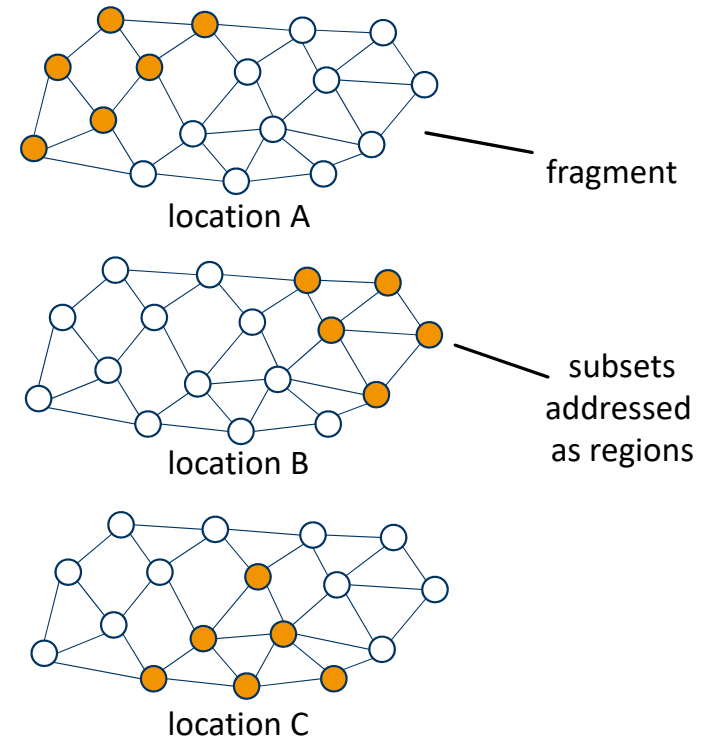
User Perspective



logical

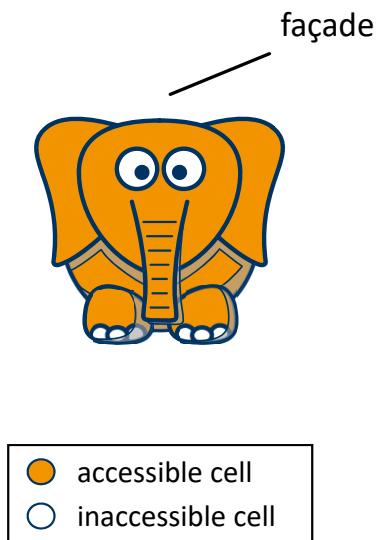
physical

Runtime System Perspective



Data Items

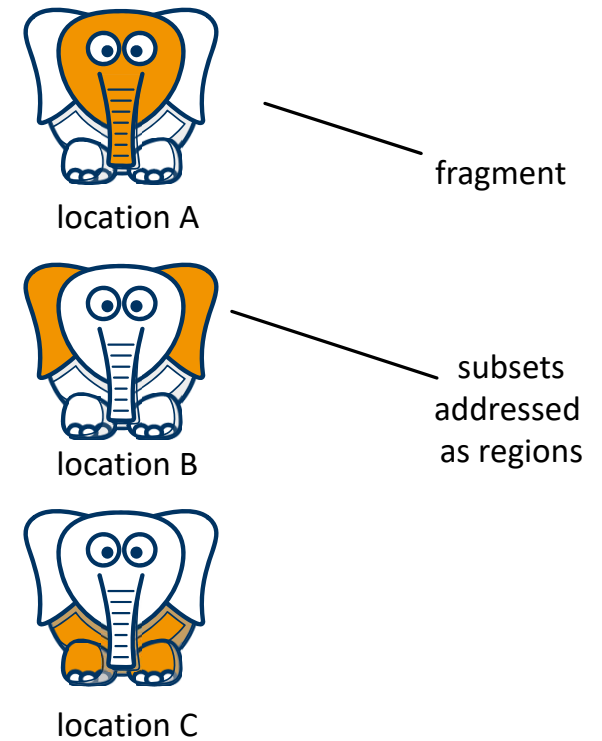
User Perspective



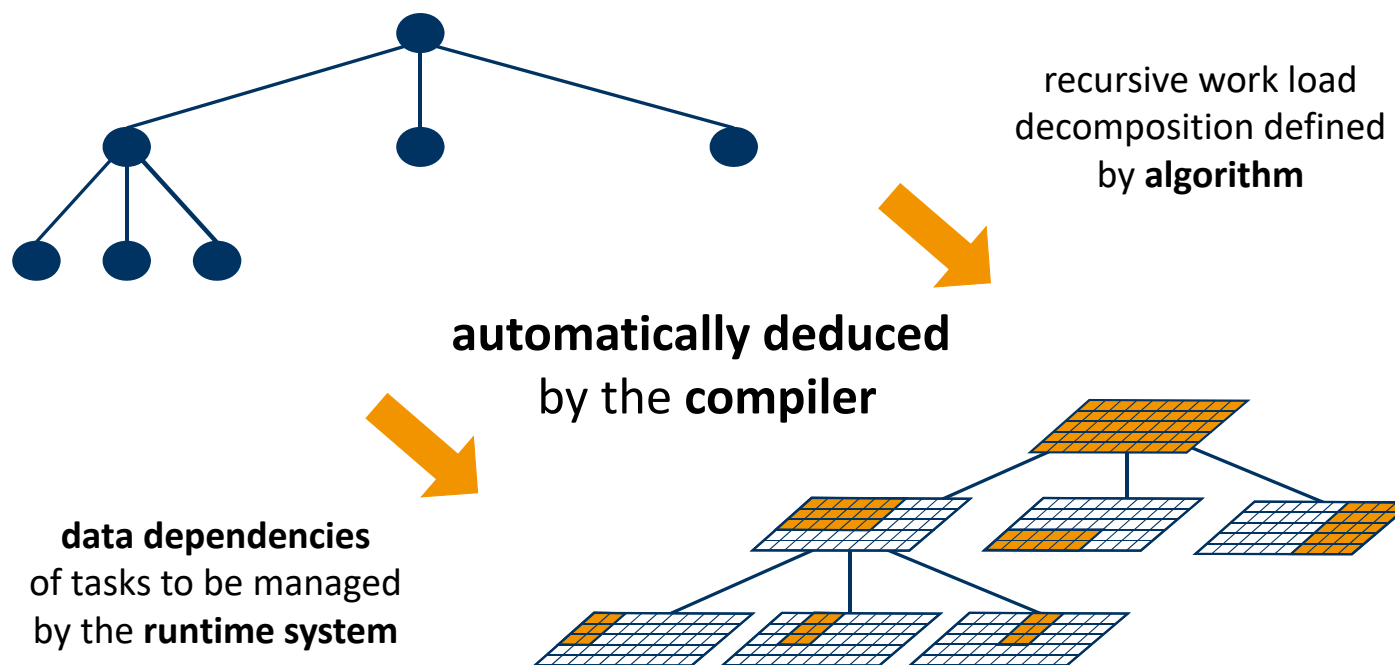
logical

physical

Runtime System Perspective



Work and Data Link



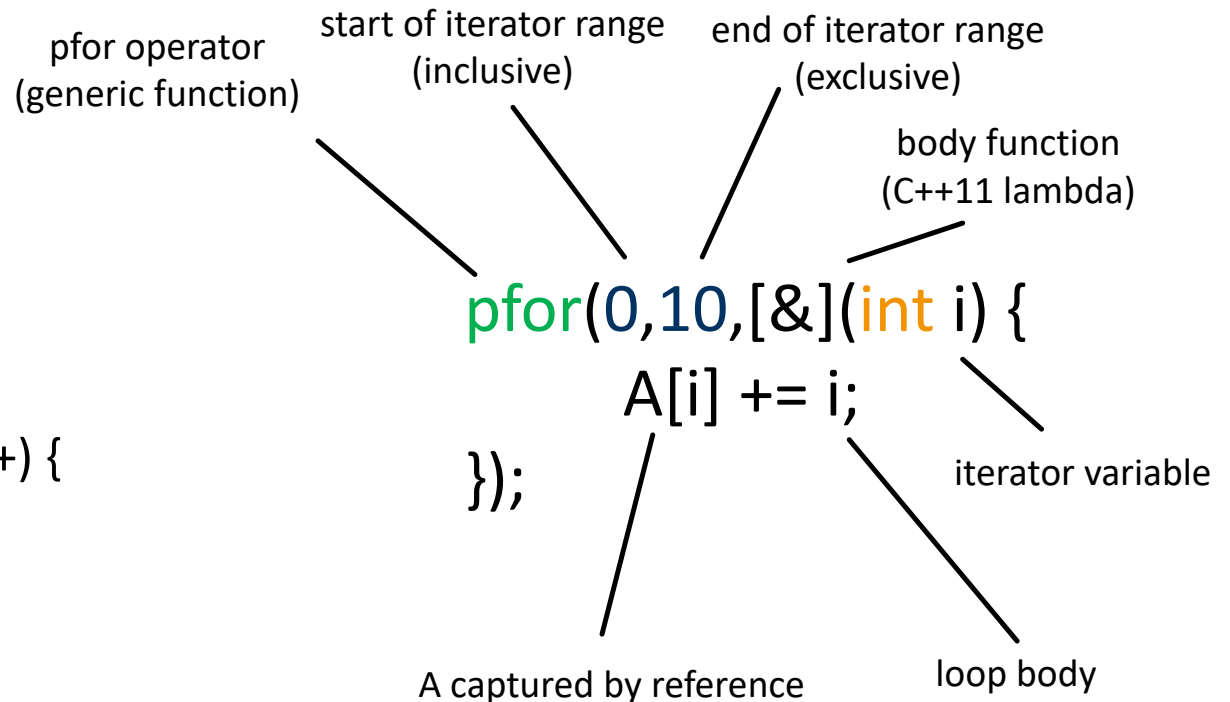
A Simple Loop

```
for (int i = 0; i < 10; i++) {  
    A[i] += i;  
}
```

Increments the first 10 elements of array A with values 0-9.

A Simple Parallel Loop

```
int rank, size;
MPI_Com_rank(COM,&rank)
MPI_Com_size(COM,&size)
int p = 10/size;
MPI_Scatter(A,...)
for (int i = p*rank; i < p*rank+p; i++) {
    A[i] += i;
}
MPI_Gather(A,...)
```



Increments the first 10 elements of array A with values 0-9 in parallel.

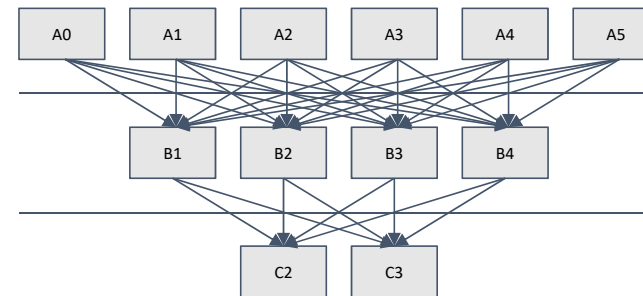
Pfor in Allscale

- Use it just like regular parallel loops:

```
pfor(0...6) a[i] = f(...);
```

```
pfor(1...5) b[i] = f(a[i-1],a[i],a[i+1])
```

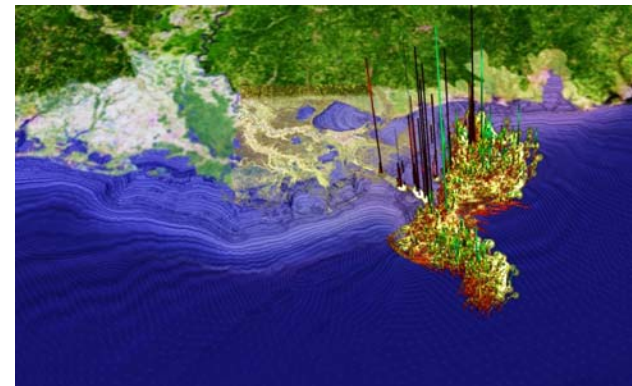
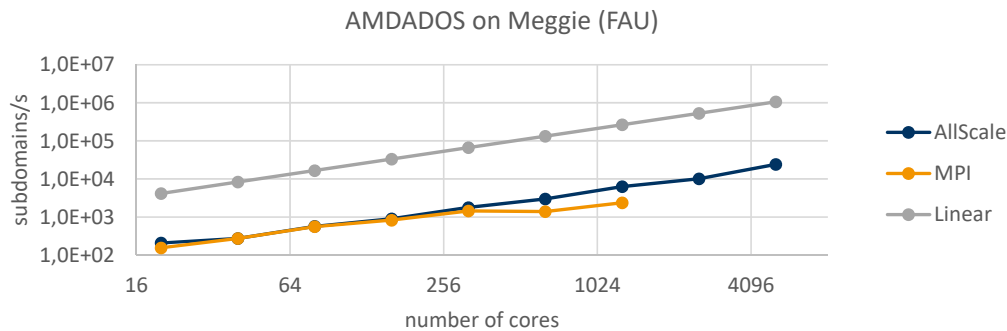
```
pfor(2...4) c[i] = f(b[i-1],b[i],b[i+1])
```



- Each of these spawns a decomposable recursive task processing the given range

AMDADOS

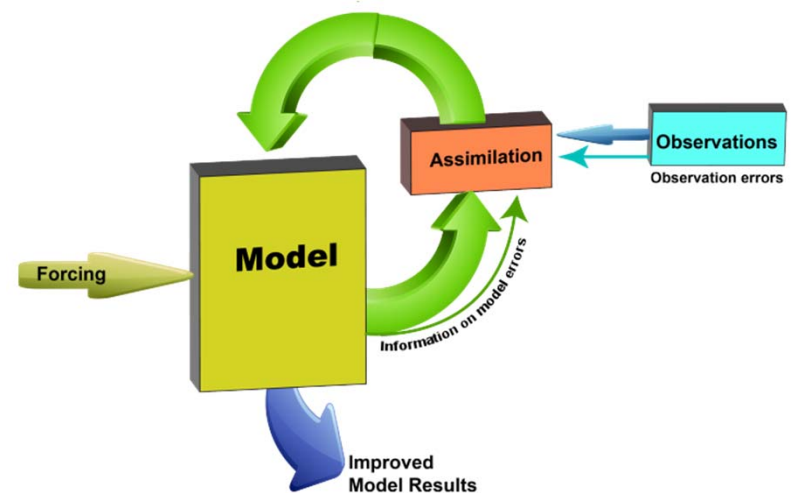
- FetHPC H2020 project AllScale
- Oil spill simulation, developed with IBM Ireland
- Stencil and kalman filter for assimilating sensor data
- AllScale exceeds performance of MPI reference implementation



Sources: <https://www.chemistryworld.com/features/oil-spill-cleanup/3008990.article>, Marcel Ritter (UIBK)

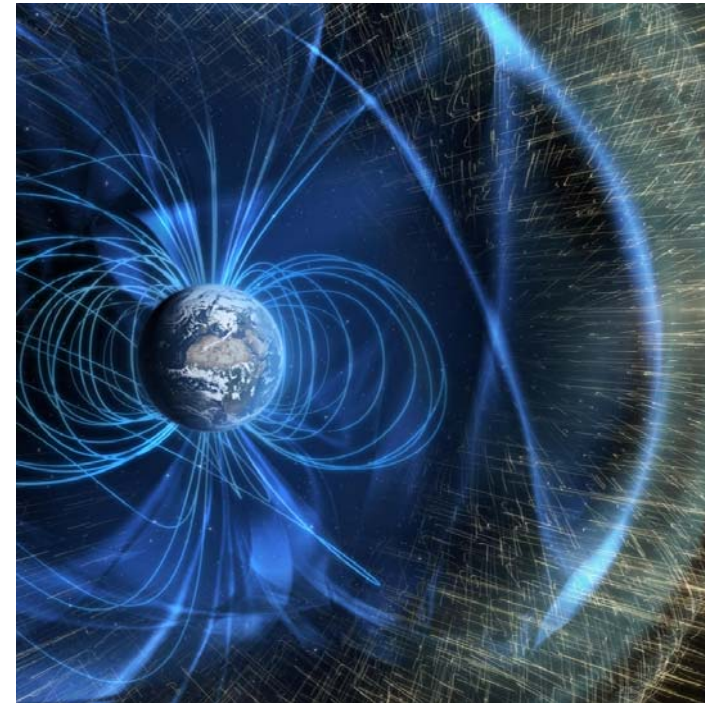
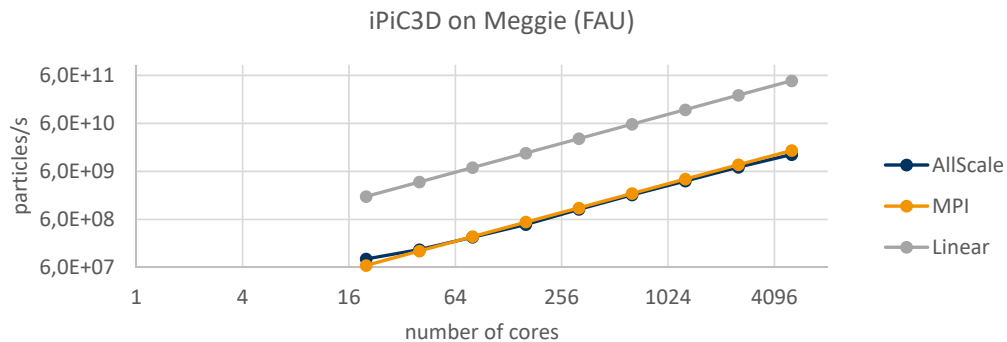
AMDADOS

- Goal: simulate oil spill in real time using advection diffusion model with data assimilation
- Data assimilation introduces large load imbalance
 - Assimilation increases computational load by a factor in the order of 10^2
- Stencil operator + adaptive mesh data item
 - Spatio-temporal parallelization
 - Refinements at observations with 3 levels of refinement



iPiC3D

- FetHPC H2020 project AllScale
- Space weather prediction, developed with KTH Stockholm
- Particle-in-Cell simulation
- Productivity improvement compared to MPI reference implementation



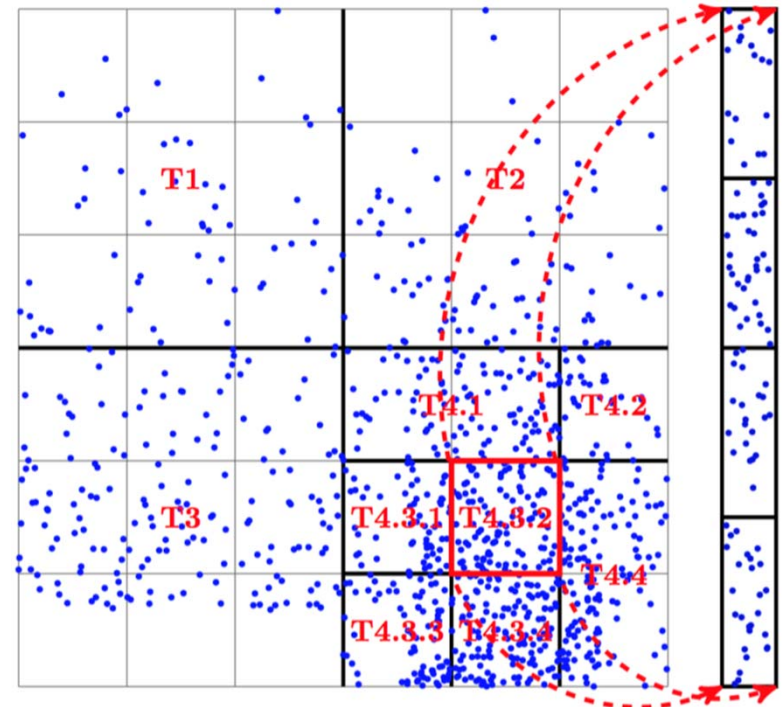
Source:
<https://twitter.com/maven2mars/status/984440044659159040>

iPiC3D

- Goal: Collision-less plasma simulation

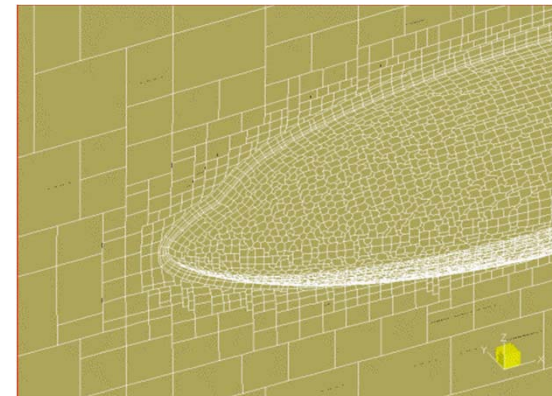
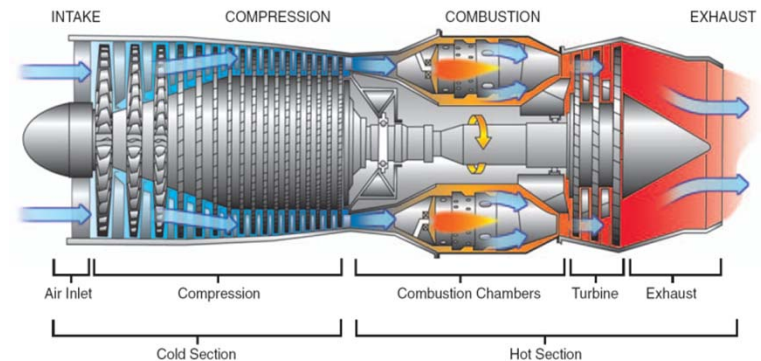
$$\frac{\partial f_s}{\partial t} + \mathbf{v} \cdot \frac{\partial f_s}{\partial \mathbf{x}} + \frac{q_s}{m_s} \left(\mathbf{E} + \frac{\mathbf{v} \times \mathbf{B}}{c} \right) \cdot \frac{\partial f_s}{\partial \mathbf{v}} = 0$$

- Compute equation of motion for charged particles and solve Maxwell's equations in turns
- Highly dynamic load imbalance due to varying particle densities
- Nested pfor operators + multiple grids



FINE/Open

- Goal: perform scalable CFD simulations for various use cases (e.g. aircraft)
- Complex configurations with several hundreds of million of points.
 - Irregular data structure
 - Many elements: cells, faces, nodes, ...
 - Even more properties: velocity, pressure, ...
- V-cycle and pfor operators + unstructured multi-level mesh



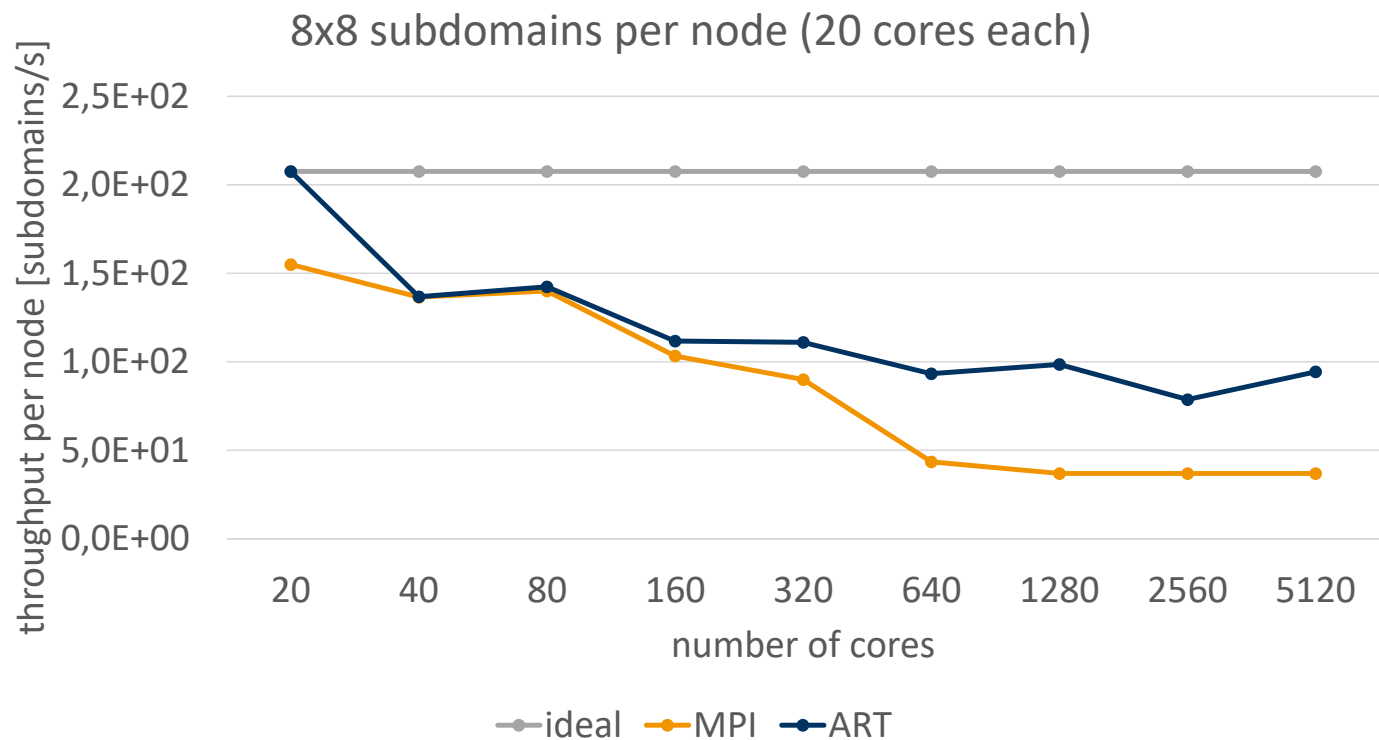
Experimental Target Systems

- Meggie (FAU)
 - 728 nodes
 - 2x Intel Xeon E5-2630 v4 (10 cores) each
 - 14,560 cores in total
 - Intel OmniPath

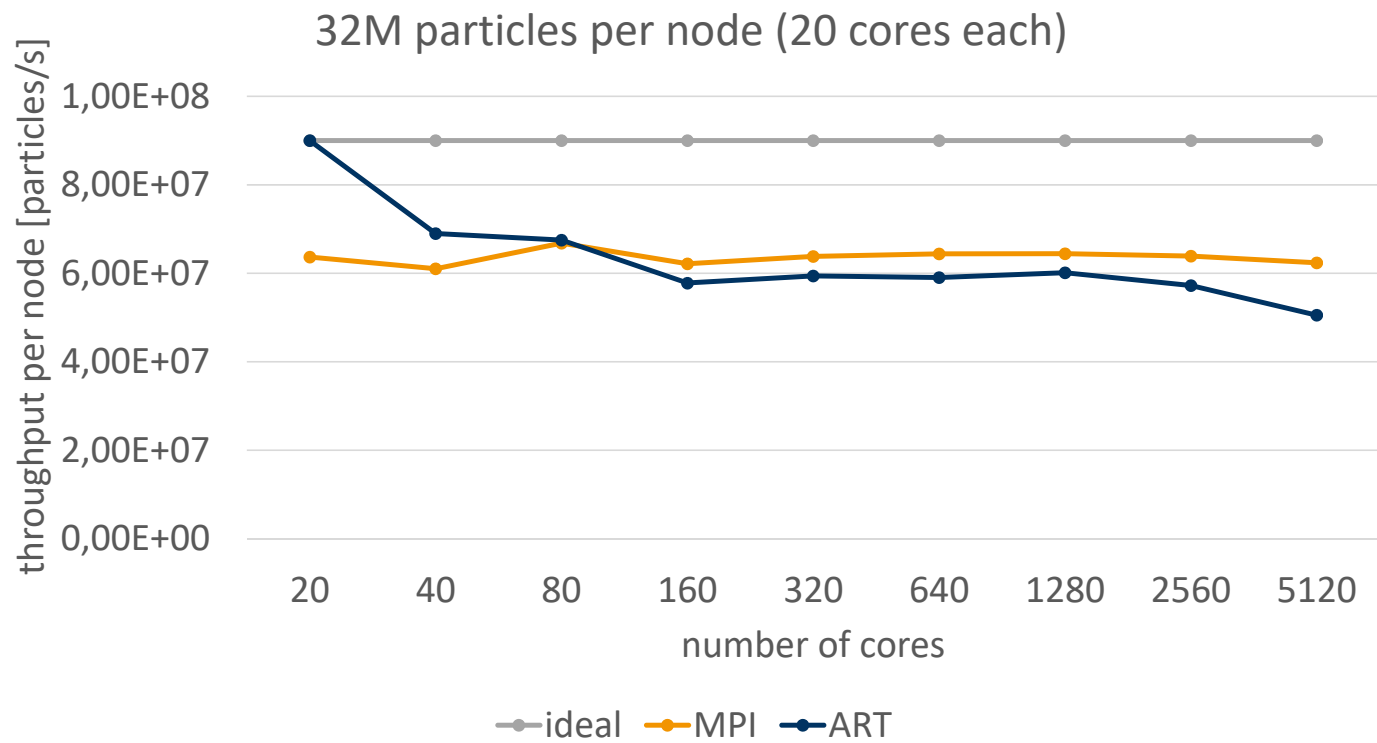
- VSC-3 (UIBK)
 - 2020 nodes
 - 2x Intel Xeon E5-2650 v2 (8 cores) each
 - 32,320 cores in total
 - QDR-80 dual-link InfiniBand



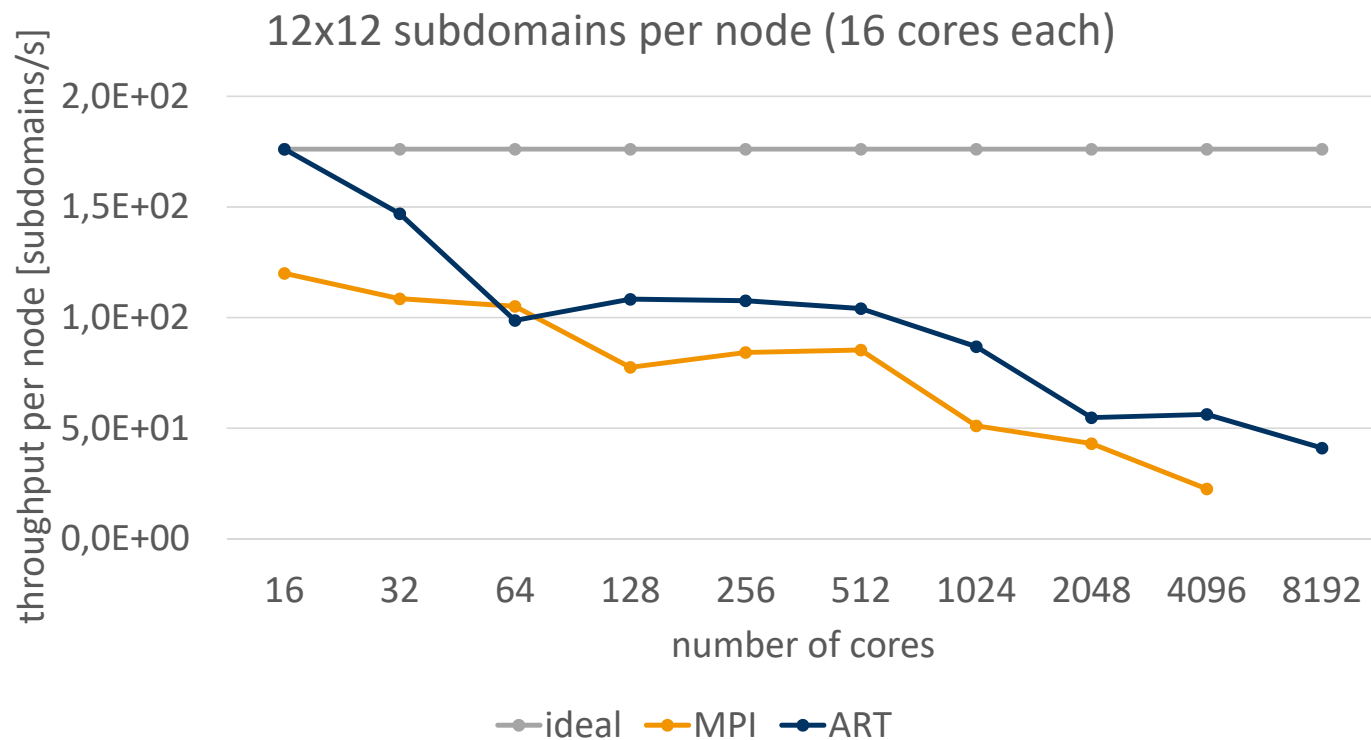
AMDADOS on Meggie



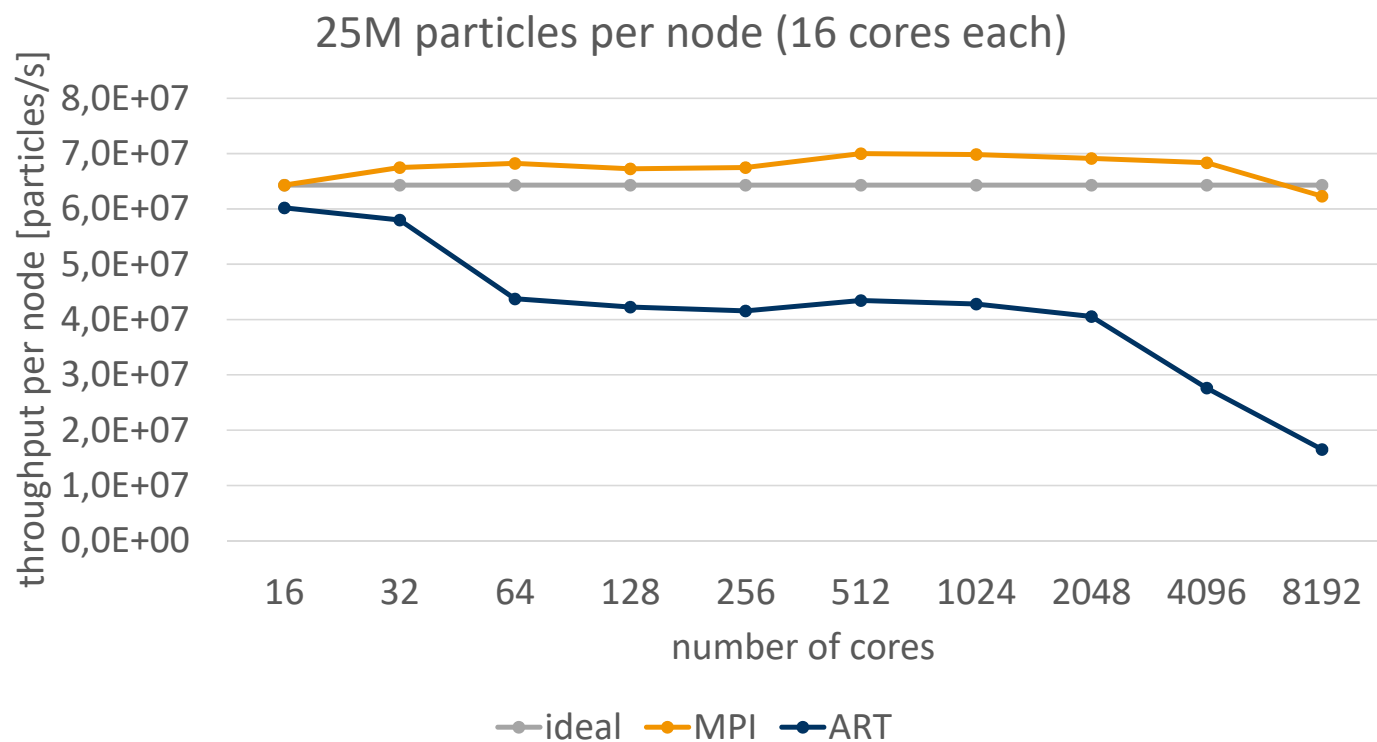
iPiC3D on Meggie



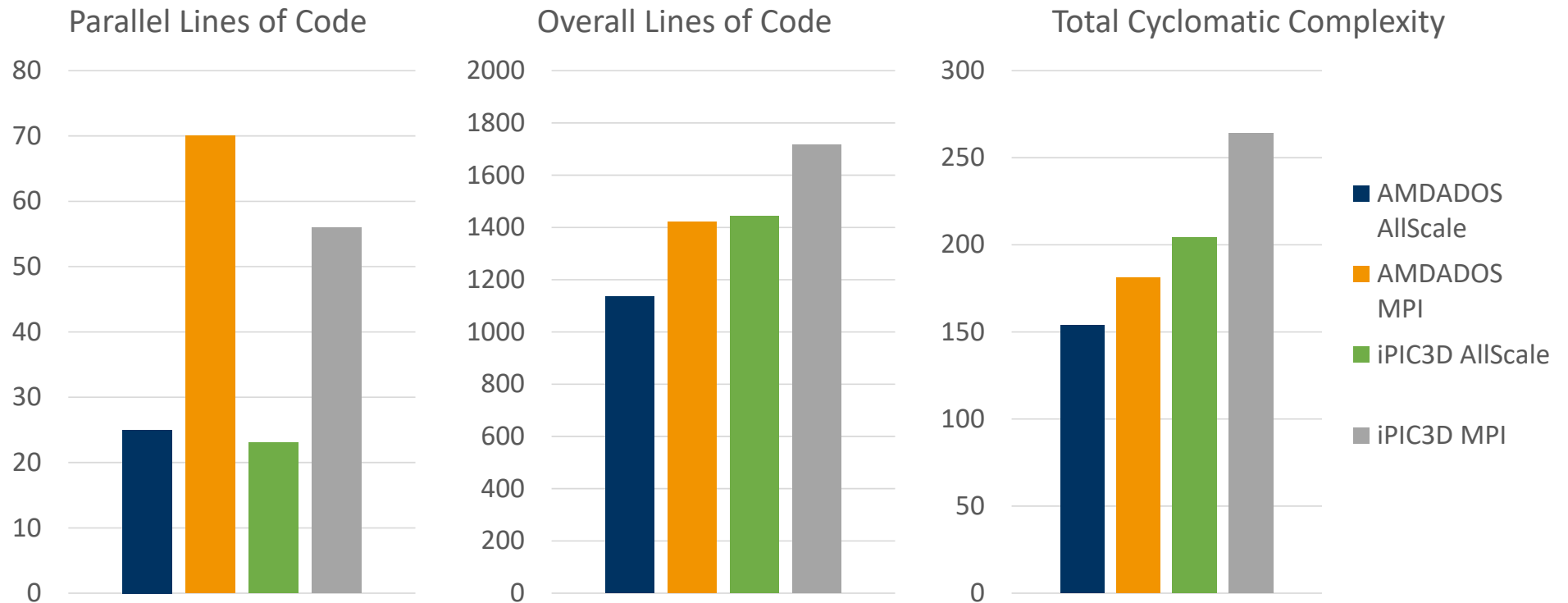
AMDADOS on VSC-3



iPiC3D on VSC-3



Productivity Evaluation



Practical Experience: Benefits and Challenges of AllScale

- | | |
|---|---|
| <ul style="list-style-type: none">▪ Higher-order primitives for parallelism and data structures to improve productivity and performance.▪ Implicit task parallelism▪ Data management out of the box▪ No explicit communication and data management▪ Automated object serialization▪ Implicit intra- and inter-node load balancing▪ No need to deal with MPI+X▪ Preserve structure of mathematical equations in the application | <ul style="list-style-type: none">▪ Requires advanced C++ knowledge▪ Longer compile times (but once for multiple runs)▪ No support for external libraries that employ non-AllScale parallelism▪ no support for accelerators so far |
|---|---|