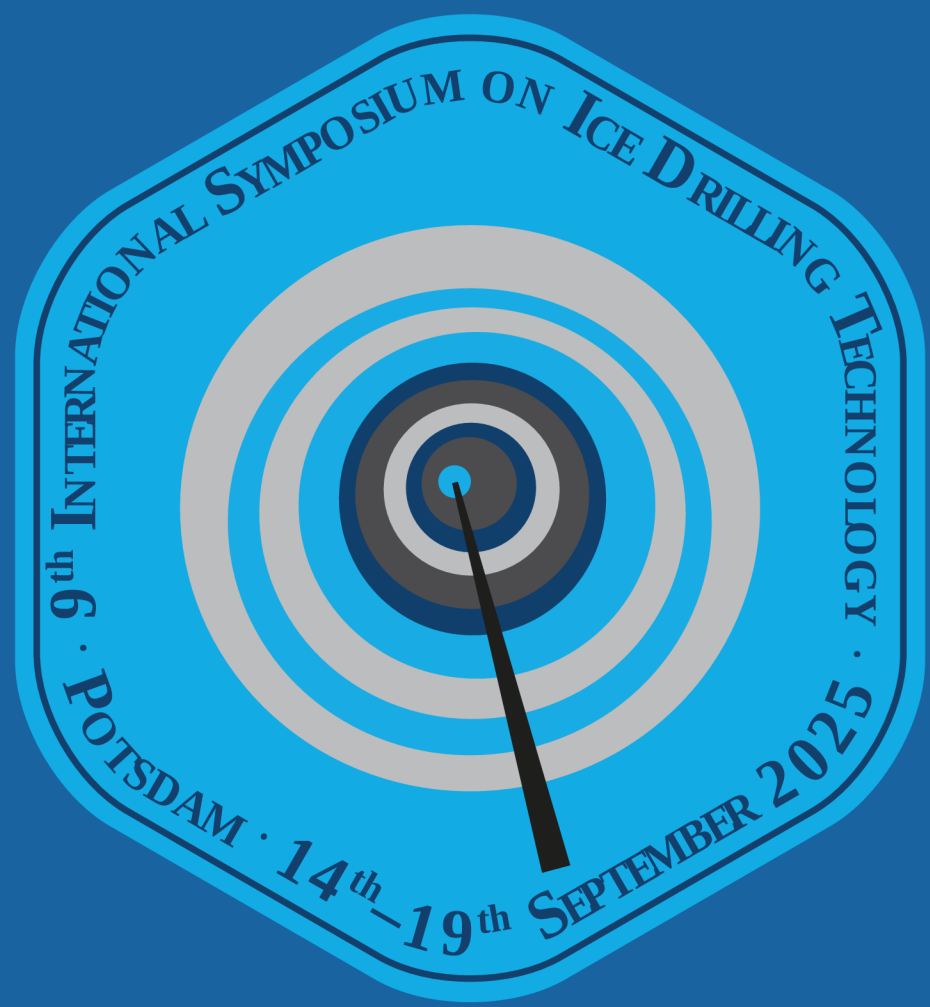


# The ISP-CNR Ice Core Drilling System: Addressing Firn Aquifers from Arctic to High-Altitude Glaciers



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Since spring 2023, during two field campaigns of the **Ice Memory project**, the ISP-CNR team, in collaboration with Ca' Foscari University of Venice, has faced major challenges in recovering shallow ice cores from wet, water-saturated firn, despite below-freezing surface temperatures. The two field campaigns were:

- **Holtedalfonna (HDF2023, Svalbard, Norway)** – late spring 2023, **Arctic** environment, **1150 m a.s.l.** 0.98 m w.e. yr<sup>-1</sup> (van Pelt et al., 2019)
- **Corbassière glacier** – Grand Combin (GC2025, Switzerland) – spring 2025, **Alps**, **4050 m a.s.l.** 1.02 m w.e. yr<sup>-1</sup> (GLAMOS, 2025)

The ISP-CNR drilling system is based on the **light series rig** from Cryosphere Research Solutions LLC, with a 300 m plastic winch cable and powered by a 3 kW generator.



**Electromechanical drill (EM100, HDF2023, GC2025)**  
Core barrel length: 110 cm  
Core diameter: 100 mm

**Electrothermal drill (ET85, GC2025)**  
Core barrel length: 200 cm  
Max core diameter: 85 mm



Results with **EM100** (HDF2023 and GC2025)  
Average recovered core length: **83 ± 20 cm**  
Average recovered core Ø: **101 ± 1 mm**  
Feed rate: **3 - 8 mm s<sup>-1</sup>**  
Production rate: **6 ± 2 m h<sup>-1</sup>**

Results with **ET85** (GC2025 only)  
Average recovered core length: **148 ± 44 cm**  
Average recovered core Ø: **84 ± 4 mm**  
Feed rate: **0.8 - 3 mm s<sup>-1</sup>**  
Production rate: **1.7 ± 0.9 m h<sup>-1</sup>**

**Dealing with partially water-filled boreholes**  
Both the EM100 and ET85 drilling systems can work underwater. However, due to the relatively low weight of the drill body (~7 kg), **additional weight** (5–10 kg) was mounted above the drill **to reduce buoyancy** (and to increase bit pressure).

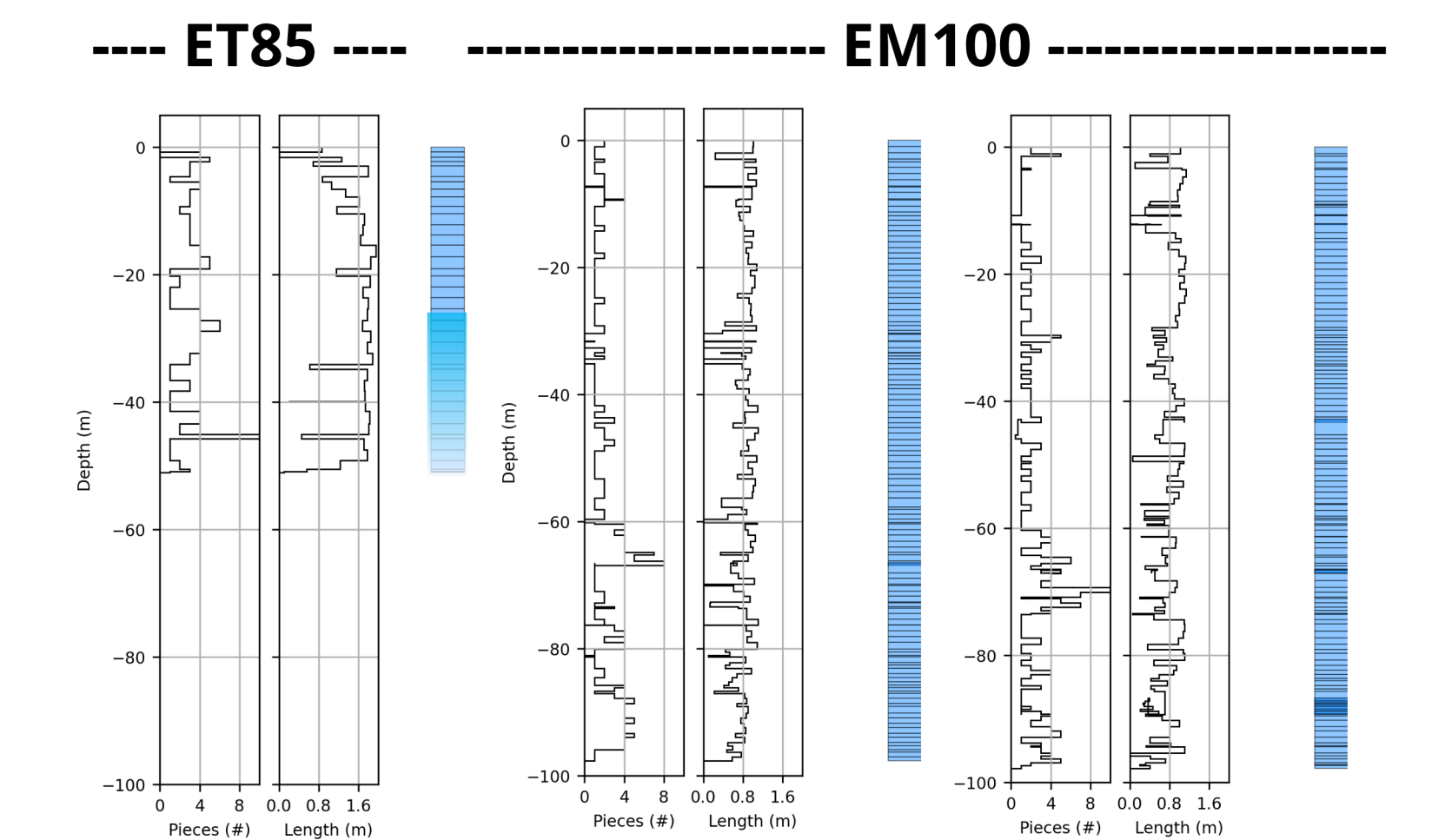
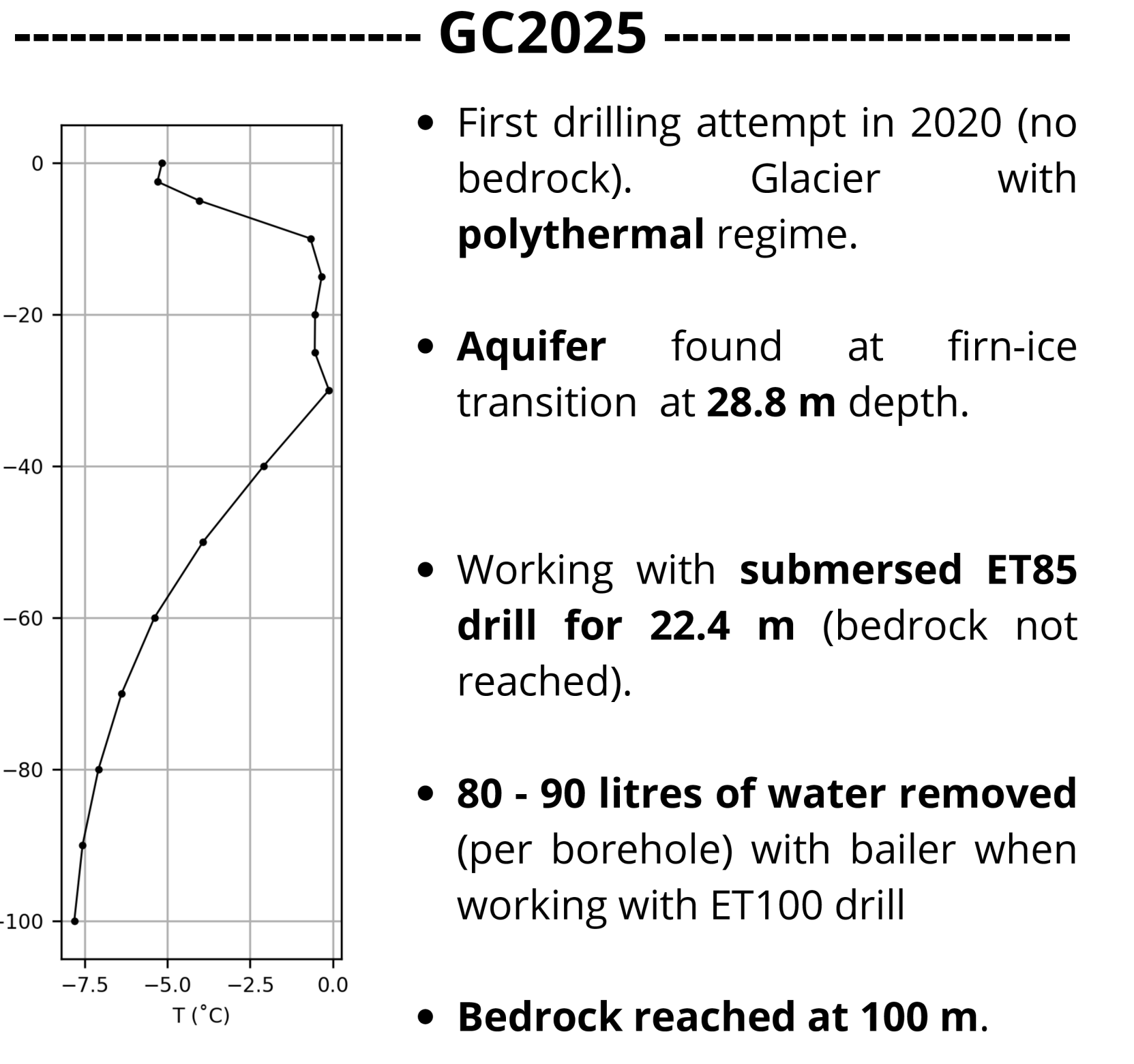
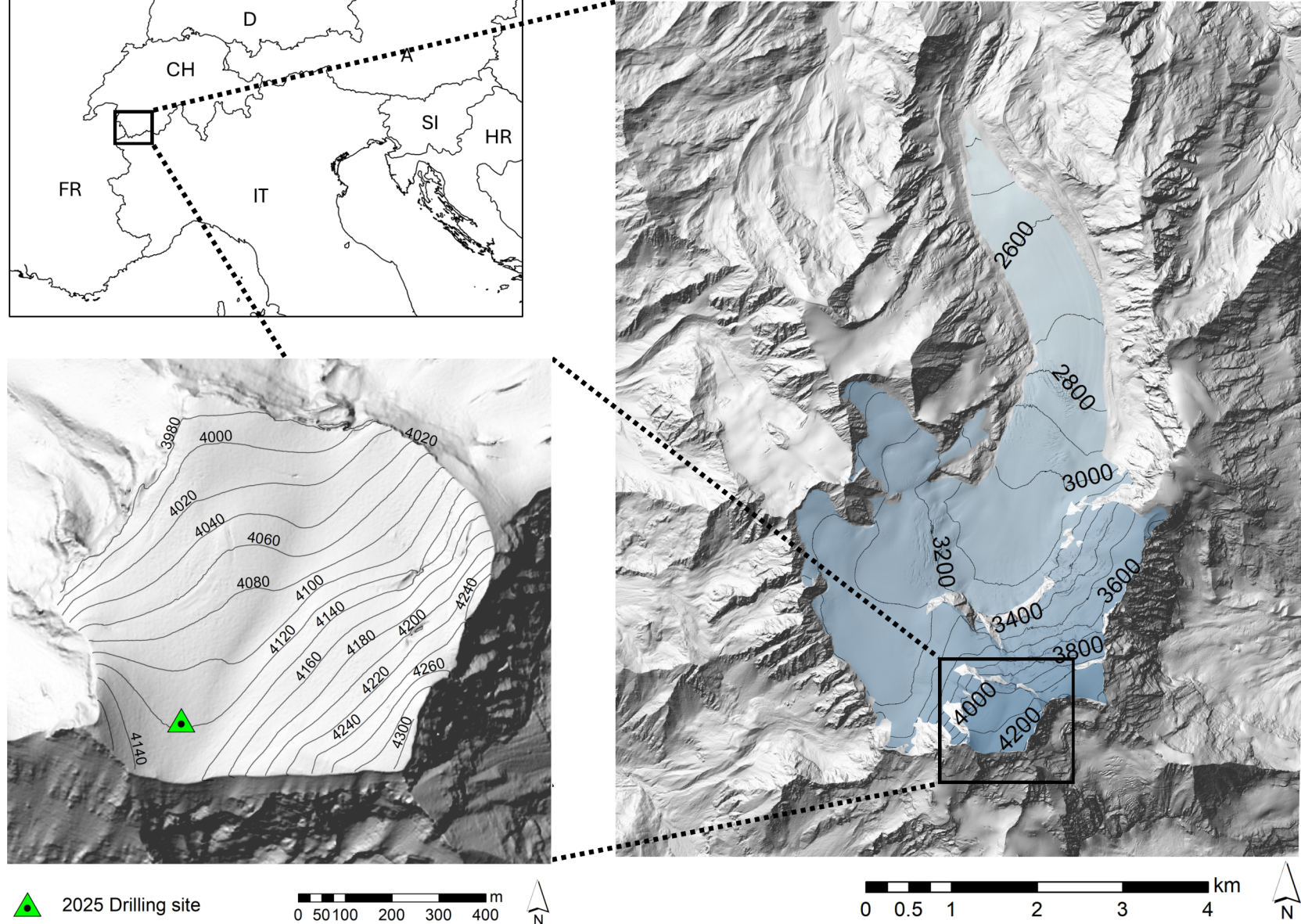
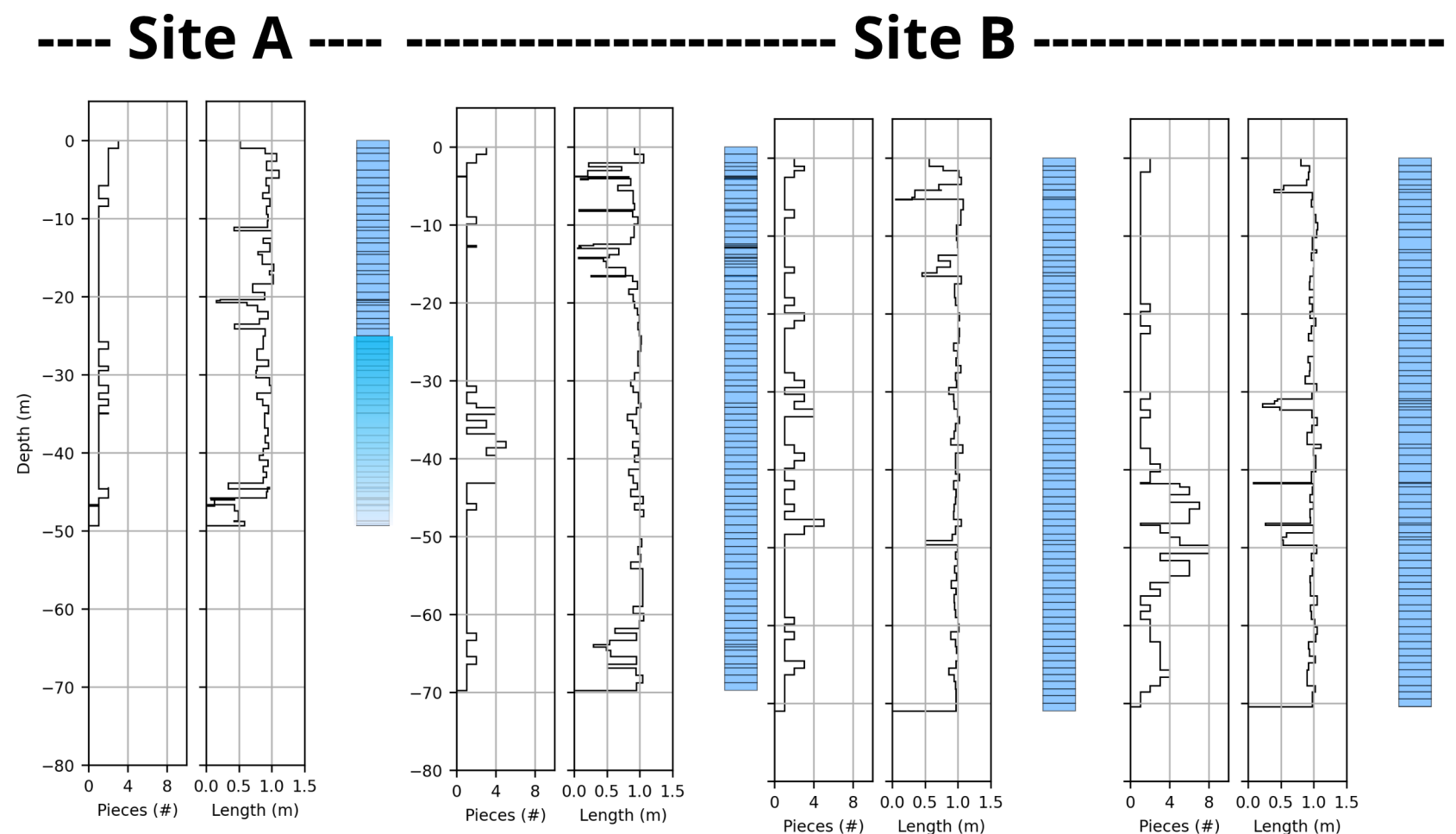
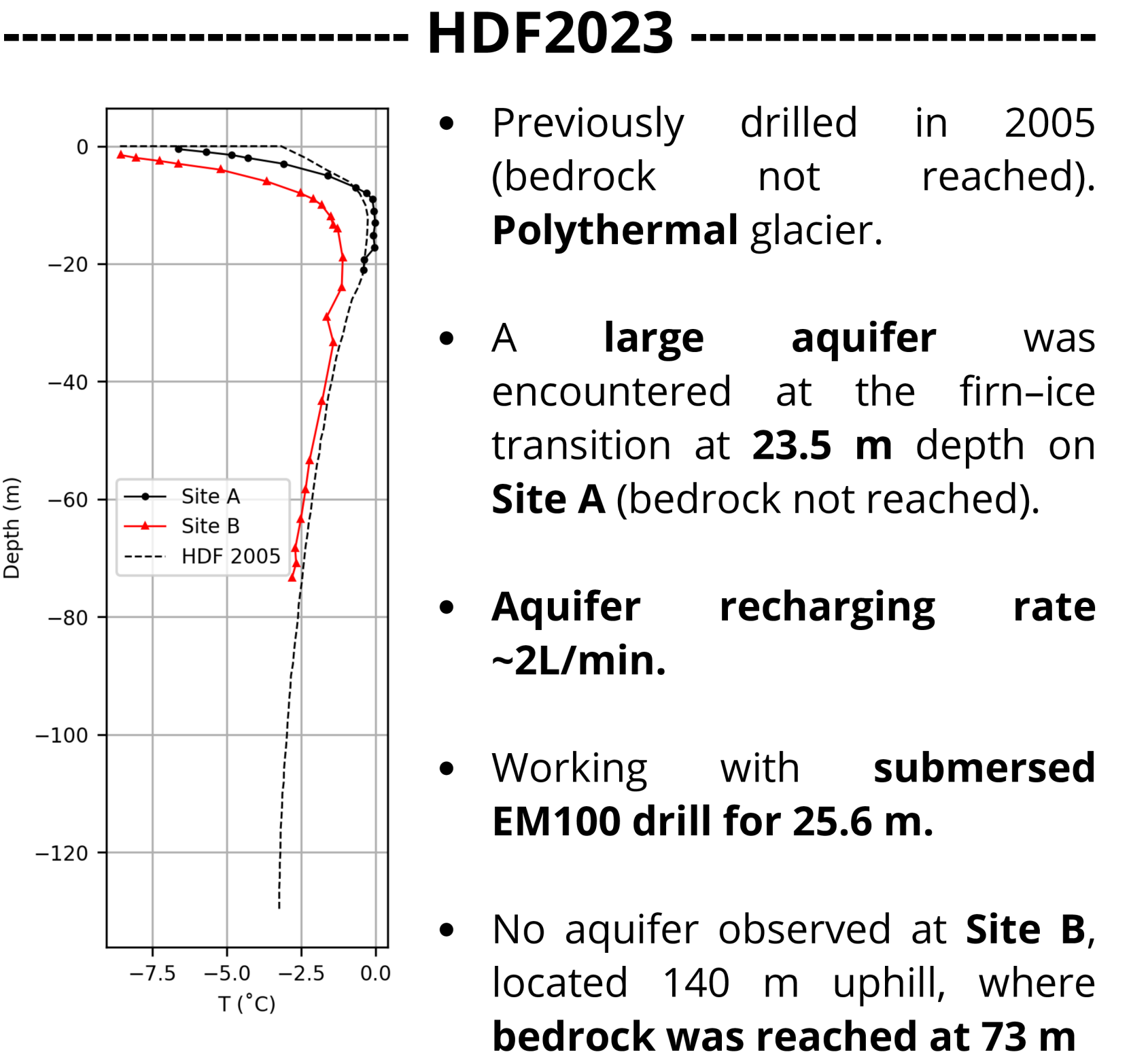
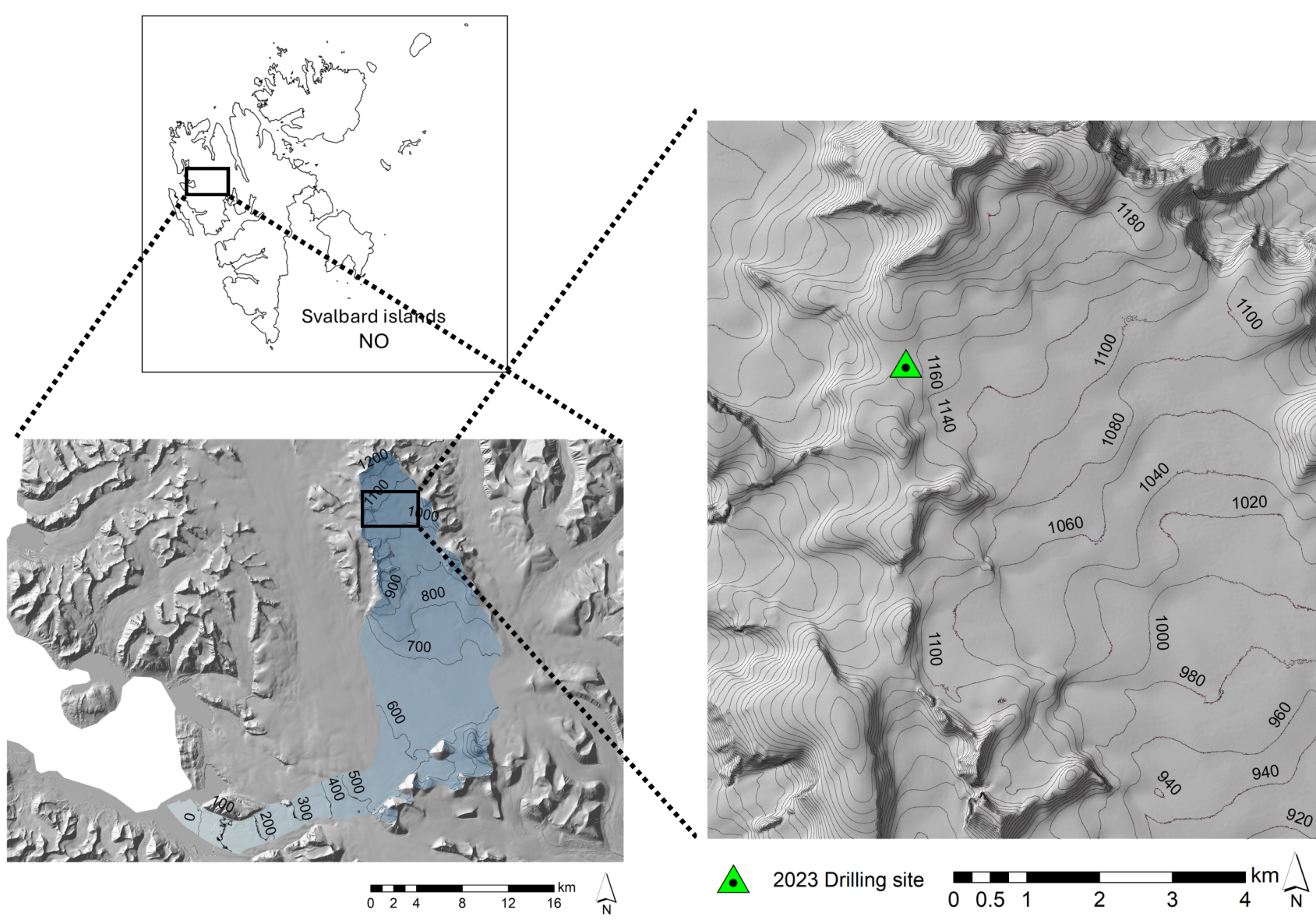
During HDF2023, a normal motor section with brushed DC motor was used (brushes were replaced frequently). During GC2025 a dedicated submersible motor section was used.

In addition, a bailer was employed **to remove meltwater** from the borehole (BH) and, when necessary, **to deploy ethanol** into the borehole kerf as an antifreeze measure (and subsequently recover it).



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## Details on the bailing system

The bailer was employed in its standard configuration during HDF2023 and GC2025 to remove water from the BH. In this setup, **each bailer run was capable of extracting up to 14 liters** of fluid from the borehole.

During GC2025, the **bailer valve system was modified to allow ethanol deployment** into the BH kerf and to **promote mixing** between ethanol and water during recovery. Specifically, the ball valve was adapted in the field with a removable latching device that prevented valve closure during the lifting phase.

Once at the surface, **the valve state could be reset** to its default configuration allowing more ethanol deployment or ethanol+water mixture recovery.

## Next steps:

- Improve weight modules, improve bailer latch valve, include gyro in drill.
- Automatic ethanol dispenser for ET drill needs more testing → tests scheduled on next season 2026
- Drilling equipment is expected to be tested on south Asia (Karakoram) in 2027

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## References:

van Pelt et al., TC, 13, 2259–2280, <https://doi.org/10.5194/tc-13-2259-2019>, 2019.  
GLAMOS data 1997 - 2024, available at <https://glamos.ch/it/factsheet#/B83-03>