

In-situ ML-based surrogate model training via continual
learning and streaming

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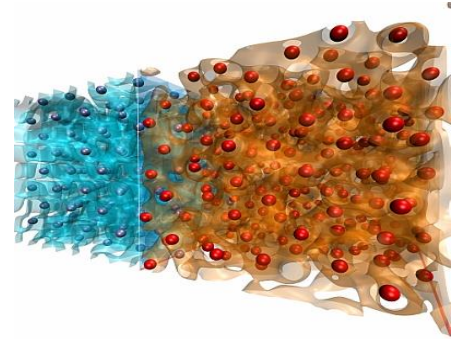
Laser Plasma Acceleration

- Building small laser facilities is of interdisciplinary interest
 - medicine
 - aerospace
 - material science
- **For practical usage full understanding of physical processes is necessary**
- Digital research environment is important
 - Planning experiments
 - Small time scales
 - High resolution



Source: HZDR.de

Modern cancer therapy



Source: Jan Vorberger

Matter under extreme condition

Plasma Simulations

Simulation

- High-resolution simulations model complex physical systems
- Simulation runs on large multi-node clusters
- Inferring effect of simulation parameters is expensive
- PIconGPU (Particle-in-Cell) is a fully relativistic, multi-core, simulation code for e.g. Laser plasma acceleration

Aim:

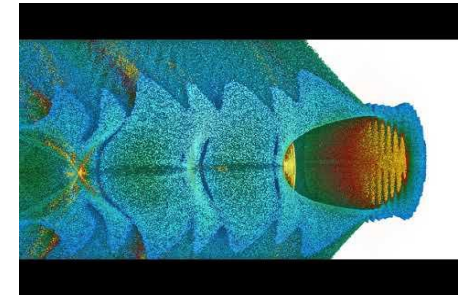
- **Train surrogate model concurrently to a running PIC simulation**
- **Approximation of numerical simulation by Reduced Order Models (ROM).**
[Talk covered by **Anna Willmann** at 1:00 PM]

System description



$$\begin{aligned}\nabla \cdot \mathbf{D} &= \rho \\ \nabla \cdot \mathbf{B} &= 0 \\ \nabla \times \mathbf{E} &= -\frac{\partial \mathbf{B}}{\partial t} \\ \nabla \times \mathbf{H} &= \mathbf{J} + \frac{\partial \mathbf{D}}{\partial t}\end{aligned}$$

System parameter



High fidelity simulation

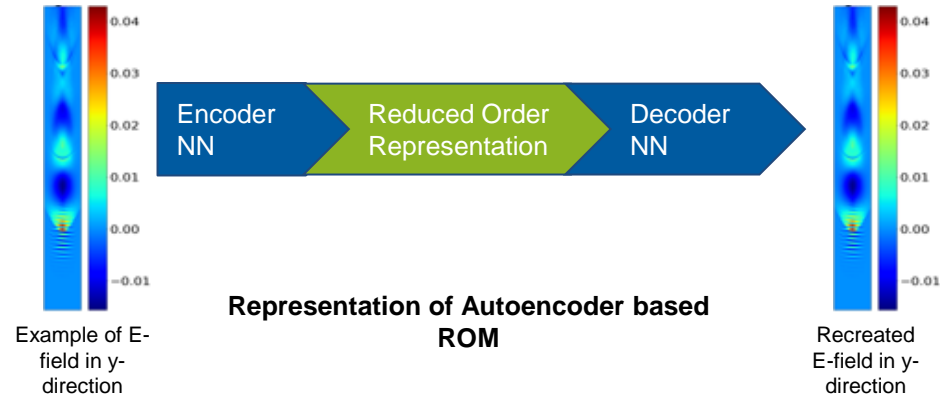
Reduced Order Model (ROM)

Reduced Order Model

- Learns an mapping in a reduced domain
- High memory compression & speed up for forward simulation

Data Generation

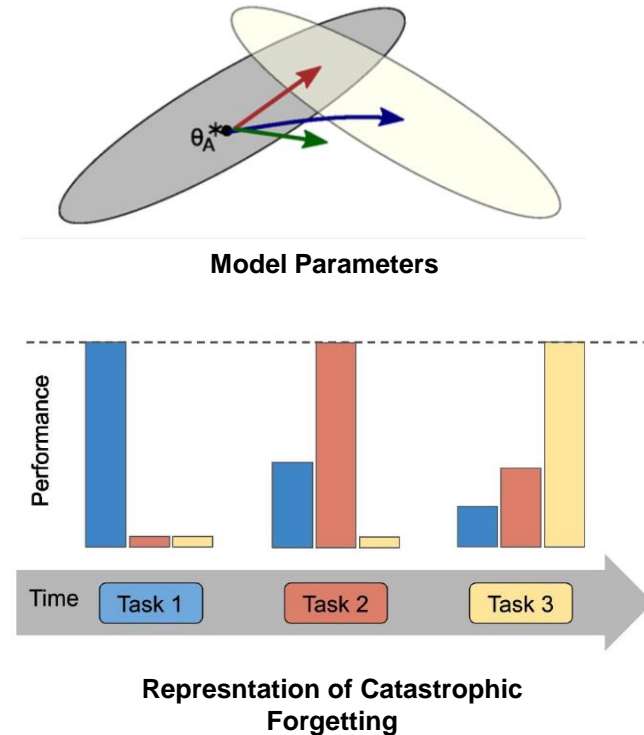
- Requires multiple simulation runs
- Massive Amount of Data
- Intensive storage for high fidelity simulation in exa-scale (10^{18}) era
- Data transfer at network speeds
- Access data in streaming fashion



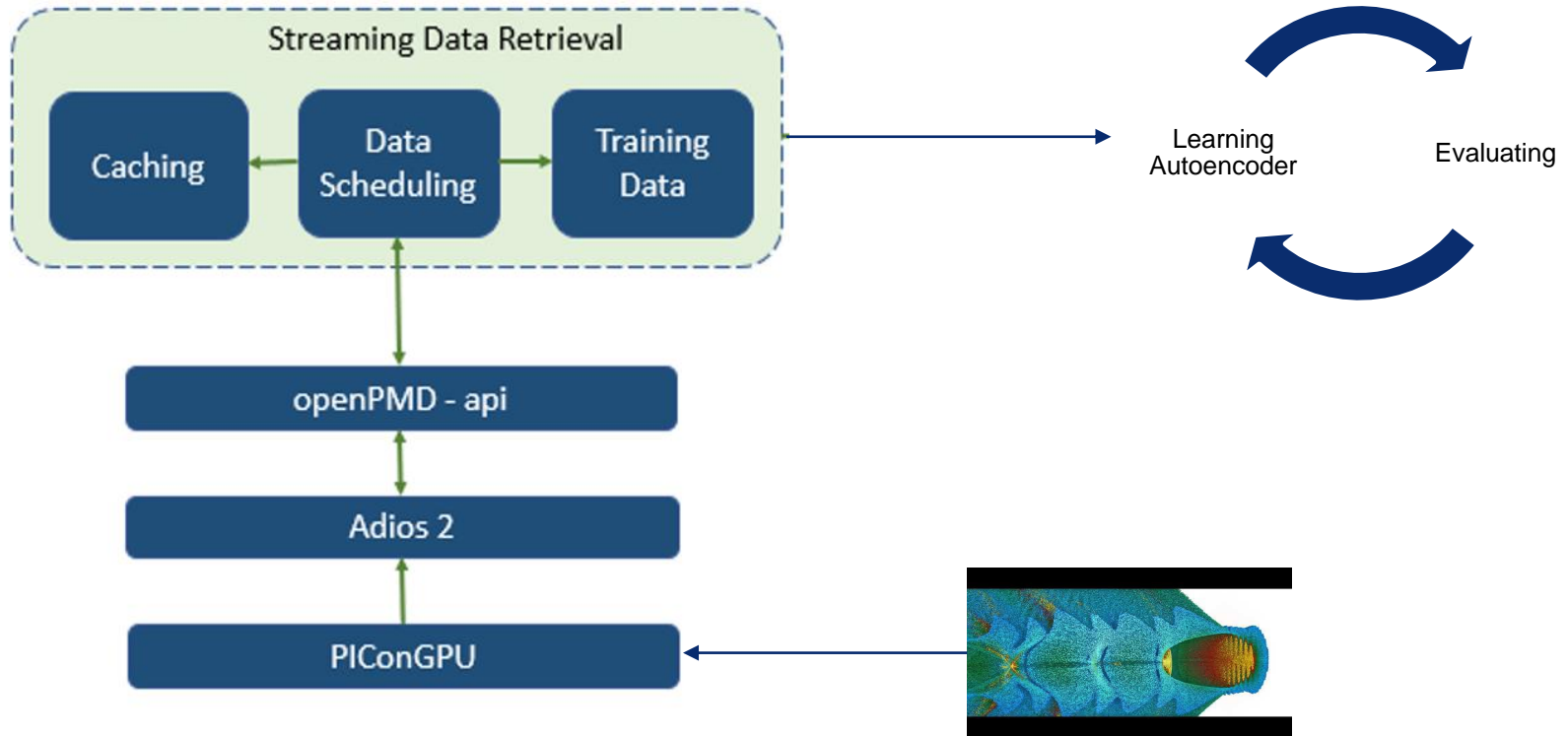
Training ROM

Continual Training

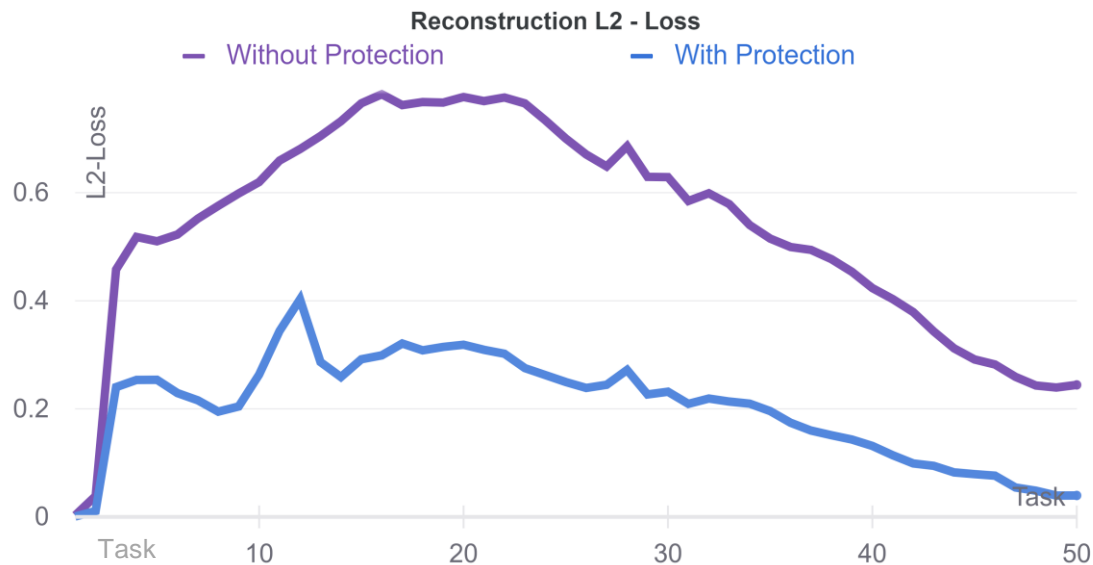
- Learning of **tasks/data** in a continuous way
- Model parameters converge on current task (data)
- High error previous tasks - **Catastrophic Forgetting** in NNs.
- Regularization and constraints on model parameters to avoid forgetting.



Current Framework ROM



Current Results



Result after training on entire stream of data
in a continual manner.

Reconstruction loss is formulated as:

$$\text{loss}_t = \left(x_t - \text{decode}(\text{encode}(x_t)) \right)^2$$
$$\forall t \in T$$

Summary

