

Uncertainty Quantification in Machine Learning

A Primer

HELMHOLTZAI

Peter Steinbach, Till Korten, Sebastian Starke, Steve Schmerler
Helmholtz-Zentrum Dresden-Rossendorf / 2024-06-11

Today's Agenda

1. Uncertainties!
2. Predictive Uncertainties
 - MCDropout
 - Uncertainty Calibration
 - DeepEnsembles
3. Use Case: Predictive Uncertainties for Instance Segmentations

Uncertainties!

What is Uncertainty?

Definition (Merriam-Webster today)

uncertainty: not known beyond doubt, not having certain knowledge, not clearly identified or defined, not constant, indefinite, not certain to occur, not reliable

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Uncertainty refers to *epistemic* situations involving imperfect or unknown information. It applies to predictions of future events, to physical measurements that are already made, or to the unknown. Uncertainty arises in partially observable or stochastic environments, as well as due to ignorance, indolence, or both.

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Uncertainties in ML for Science (Tan *et al.*, 2023)

npj

A.R. Tan *et al.*

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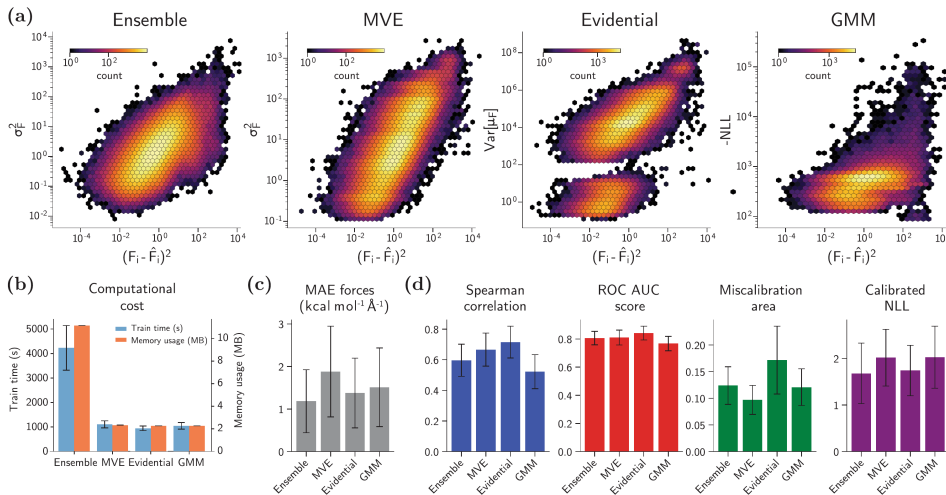


Fig. 1 Comparison of UQ methods on the rMD17 data set. a Hexbin plots showing (predicted) uncertainties versus squared errors of atomic

Uncertainties: a paradigm shift in the ML community

*Let's say I have data and I fit a linear model to predict y from xSo that would be the predictive take. The inferential take would be: can I say something about which features are significant in this (linear) model? Can I actually give under some assumptions **a confidence interval** for their coefficient in the linear model and so on.*

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*And historically in machine learning, inference may have been very, very small. And now I think it's grown in a way that people do talk about inference, they use the word **uncertainty quantification**. They don't think about inference and typically in the traditional way statistically. But I think it has somehow emerged as maybe more of a focus.*

Ryan Tibshirani in "The Gradient Podcast", see [here](#) for the full interview.

Origins of Uncertainty in ML 1/3

Supervised Machine Learning

- *dataset* $\mathcal{D} = \{(\vec{x}_0, y_0), (\vec{x}_1, y_1), \dots, (\vec{x}_N, y_N)\} \subset \mathcal{X} \times \mathcal{Y}$
 - \mathcal{X} ...instance space
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- given a *loss function* $l : \mathcal{X} \times \mathcal{Y} \rightarrow \mathbb{R}$

Origins of Uncertainty in ML 2/3

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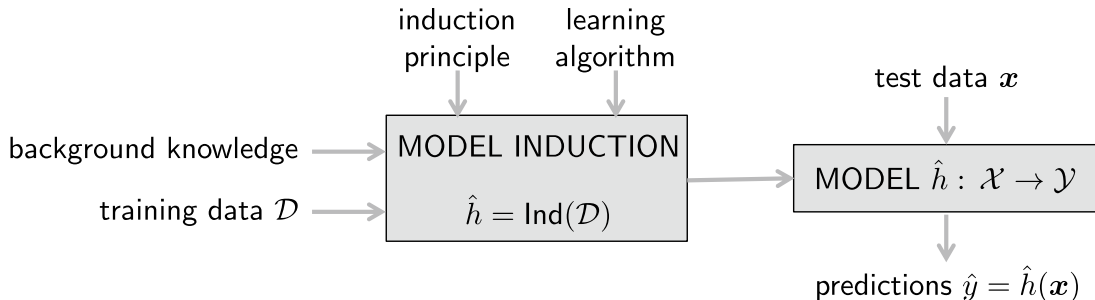
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R_{emp} only estimates R !

- $h^* := \arg \min_{h \in \mathcal{H}} R(h)$ will not coincide with $\hat{h} := \arg \min_{h \in \mathcal{H}} R_{emp}(h)$
- **uncertainty created!** what is h^* ? How close is \hat{h} to h^* ? What is $R(\hat{h})$?

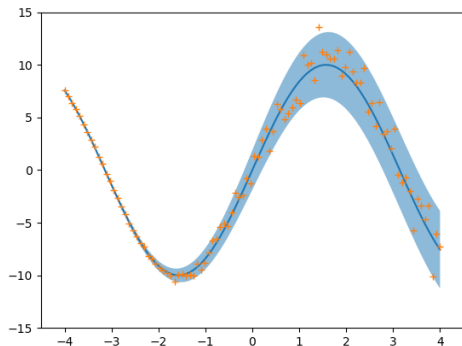
Wrap-Up Origins of Uncertainty (Hüllermeier & Waegeman, 2021)



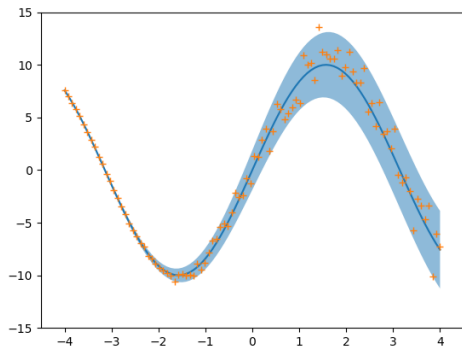
Central Point of Interest: **Predictive Uncertainties**
(uncertainty for $y_q = \hat{h}(x_q)$ for a concrete instance $x_q \in \mathcal{X}$)

Predictive Uncertainties

A historic view on Uncertainty sources

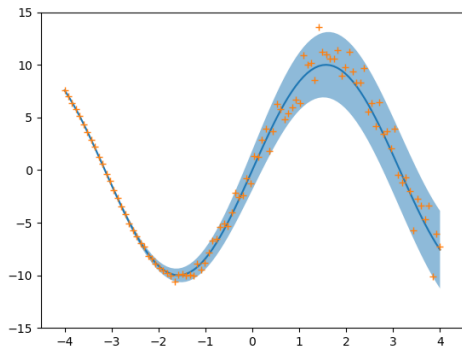


A historic view on Uncertainty sources



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Data related **uncertainty**
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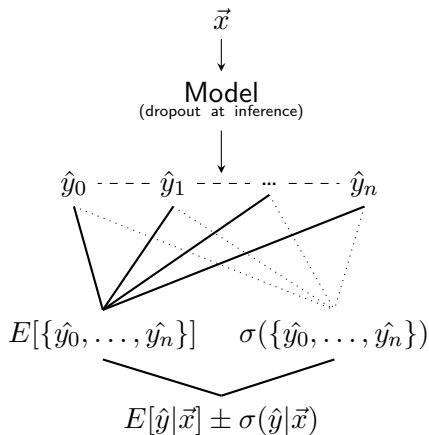
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- **Aleatoric** or
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- **Epistemic** or
Model related **uncertainty**
(uncertainties related to finding the
best hypothesis, can be reduced with
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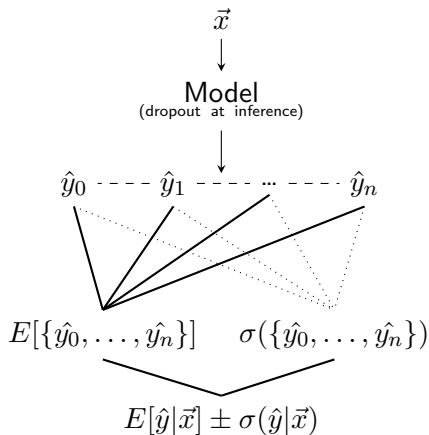
Obtaining (epistemic) Uncertainties (Gal & Ghahramani, 2016)

Monte Carlo Dropout



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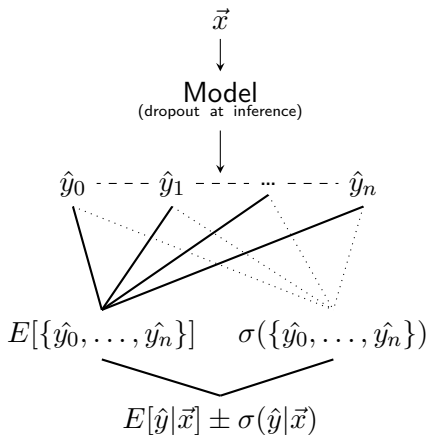
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(implicit regularisation during training)

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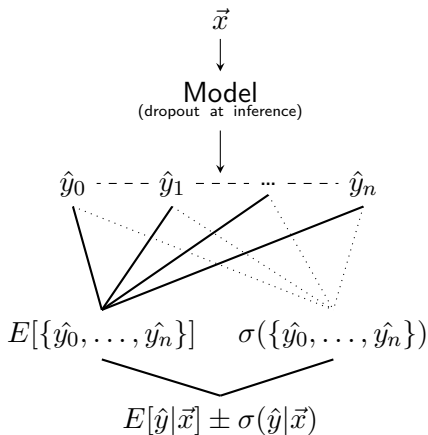
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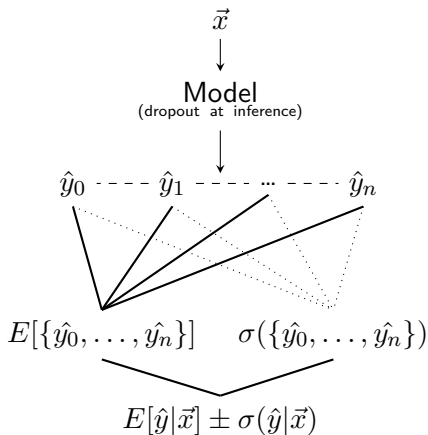
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- obtain mean prediction $E[\hat{y}]$ and prediction deviation $\sigma(\hat{y})$ for each input

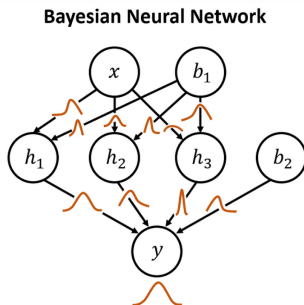
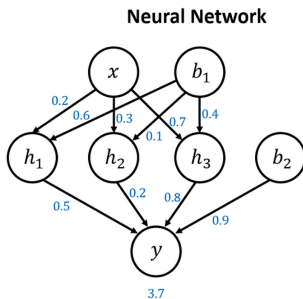
Try MCDropout for yourself

Please open

`mcdropout_1D_regression_vanilla.ipynb!`

Go through the notebook.

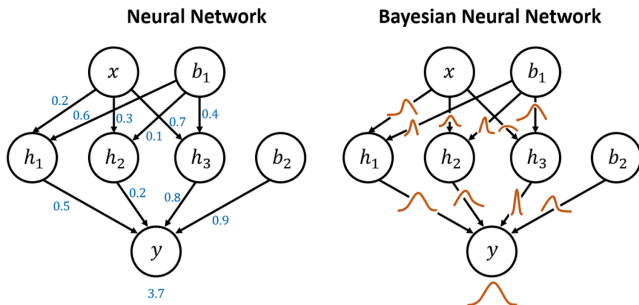
Dropout Recap



- MCDropout approximates a Bayesian Neural Network (BNNs are computational intensive)

from jonascleveland.com

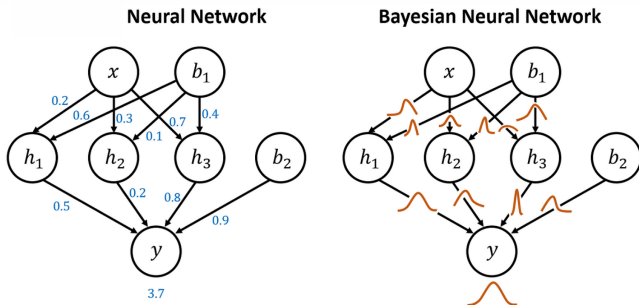
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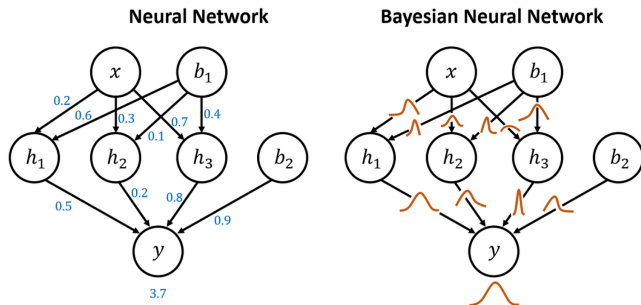
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see ([Gawlikowski et al., n.d.](#)) for details

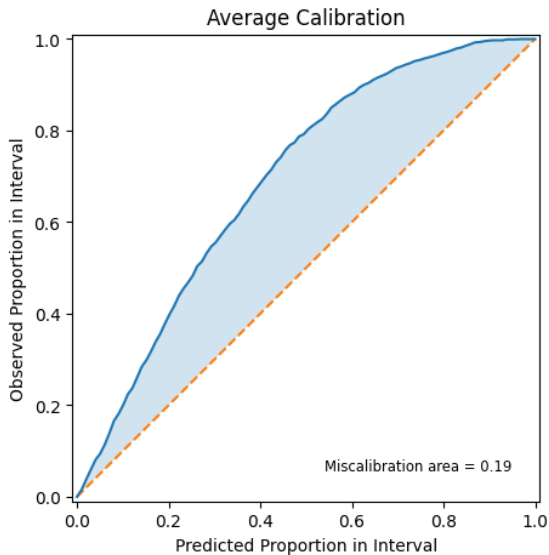
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- **epistemic uncertainties**

Diagnosing a UQ method: Calibration Curves



How to judge predictive uncertainties? (Kuleshov *et al.*, 2018)

At Inference, we have

- a label y_{test}
- a prediction $E[y_{test}]$ (by our model)
- an uncertainty for that prediction $\sigma_{y_{test}}$ (from the UQ method)

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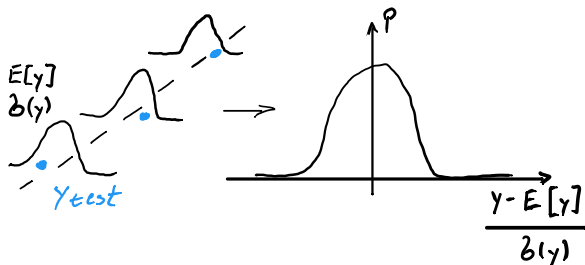
Assumption

- $E[y_{test}]$ and $\sigma_{y_{test}}$ model a gaussian distribution around y_{test}

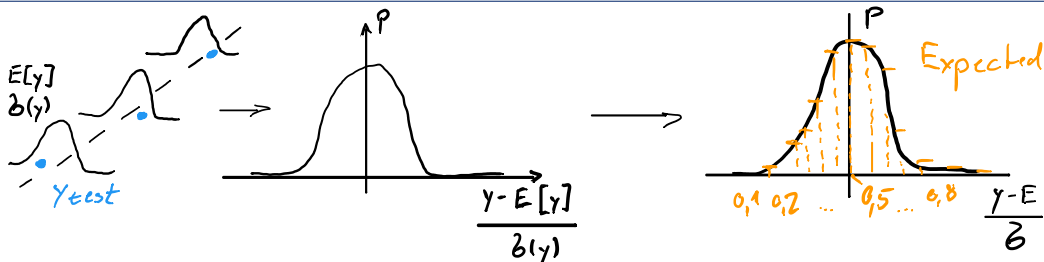
Calibration in a nutshell (Kuleshov *et al.*, 2018)



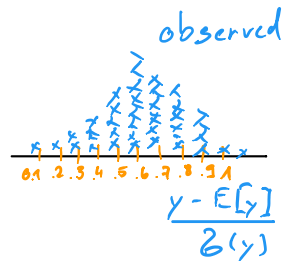
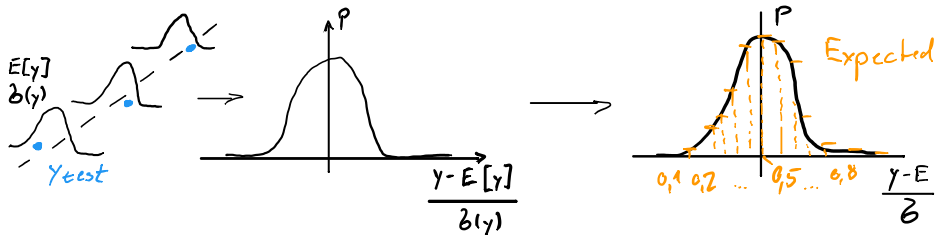
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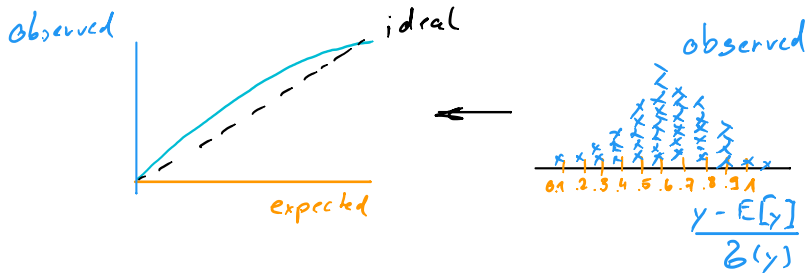
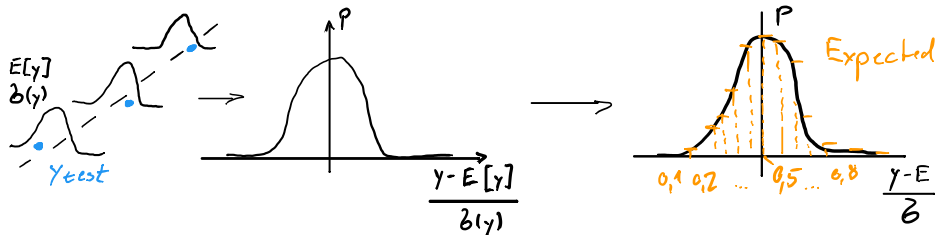
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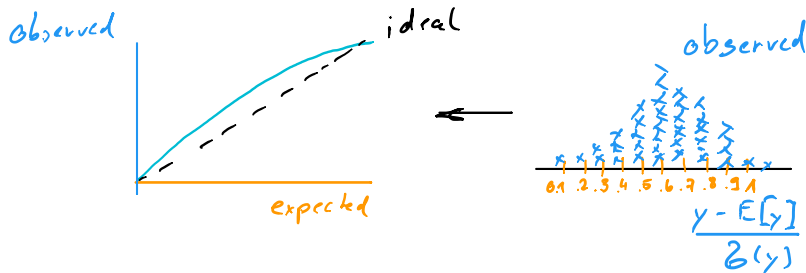
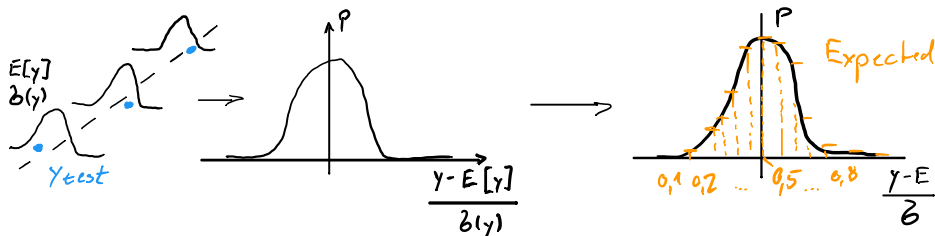
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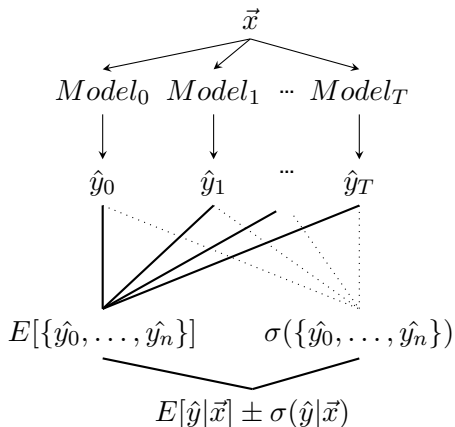
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Note: only sufficient criteria for uncertainty quality (Levi et al., 2020)!

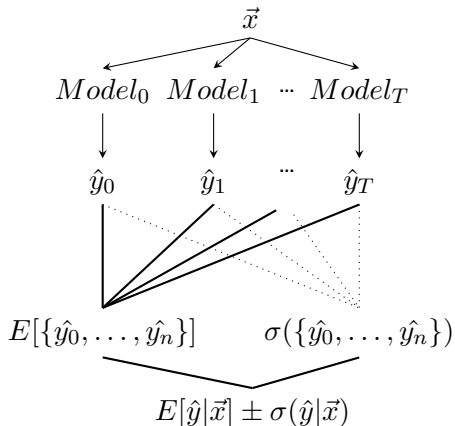
Obtaining Uncertainties in Ensembles (Lakshminarayanan *et al.*, 2017)

Deep Ensemble?



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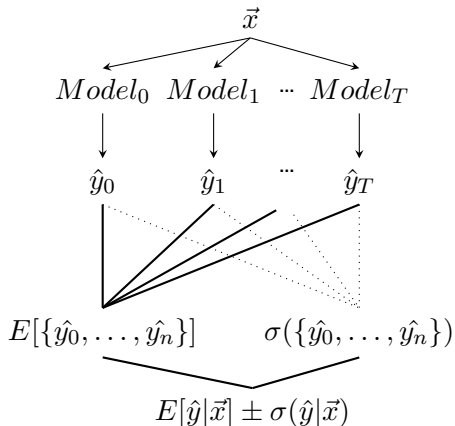
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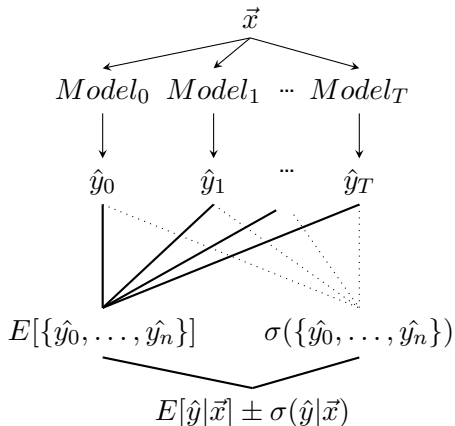
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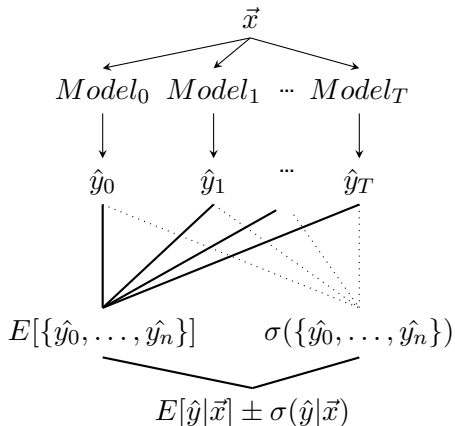
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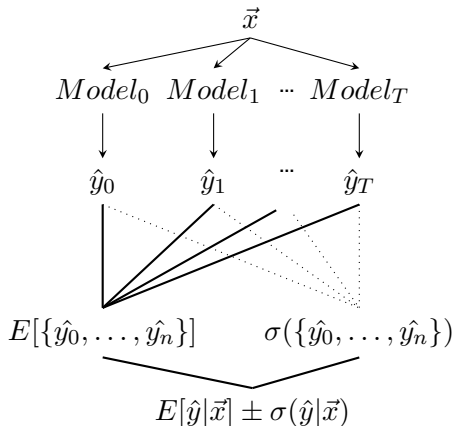
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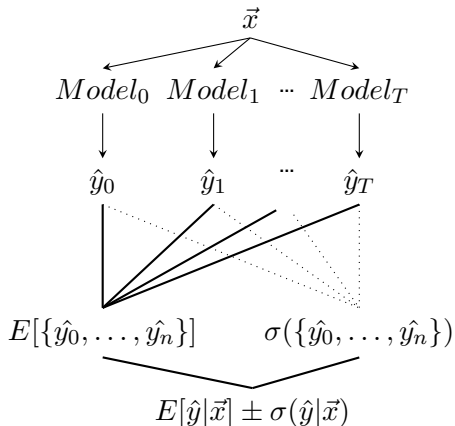
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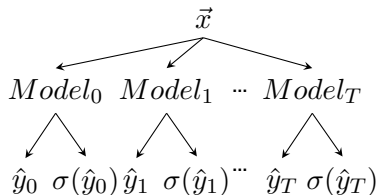
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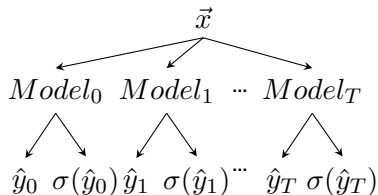
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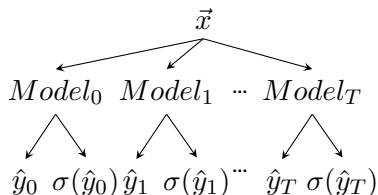
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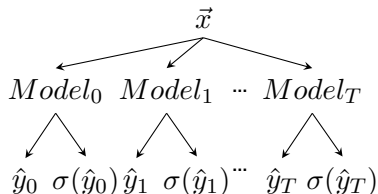
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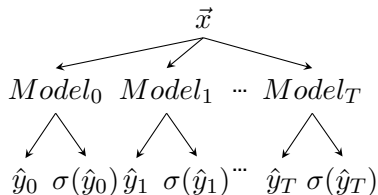
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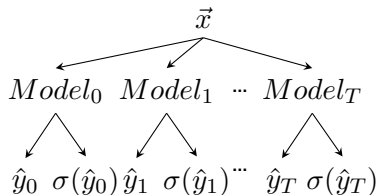
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Obtaining Uncertainties in Ensembles (Lakshminarayanan *et al.*, 2017)

Deep Ensemble!



$$l_{nll} = -\log p = \frac{\log \sigma(\hat{y})^2}{2} + \frac{1}{2} \frac{(y - \hat{y})^2}{\sigma(\hat{y})^2}$$

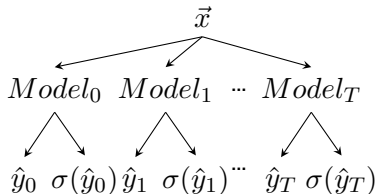
$$E_{ens}[y_n] = \frac{1}{T} \sum_{t=0}^T \hat{y}_t$$

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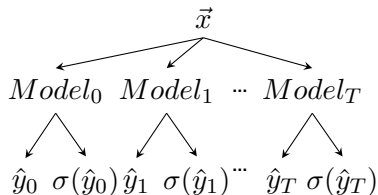
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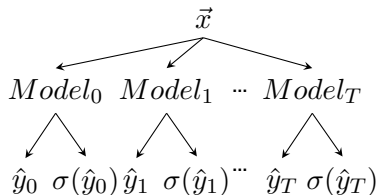
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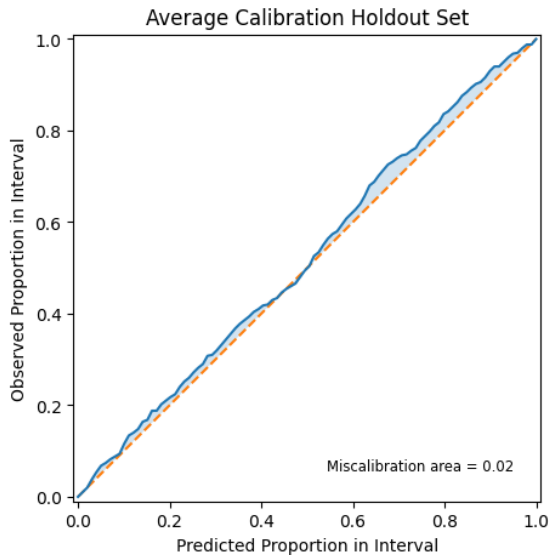
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 - but: different loss, different model
- These are “Deep Ensembles”!**

Try Deep Ensembles for yourself

Please open
`deepensembles_1D_regression_vanilla.ipynb`
Go through the notebook.

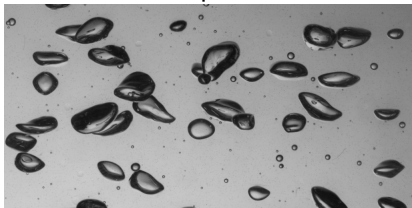
Well Calibrated Uncertainties with DeepEnsembles



Use Case: Predictive Uncertainties for Instance Segmentations

Instance Segmentation Task

Input



(Hessenkemper *et al.*, 2022)

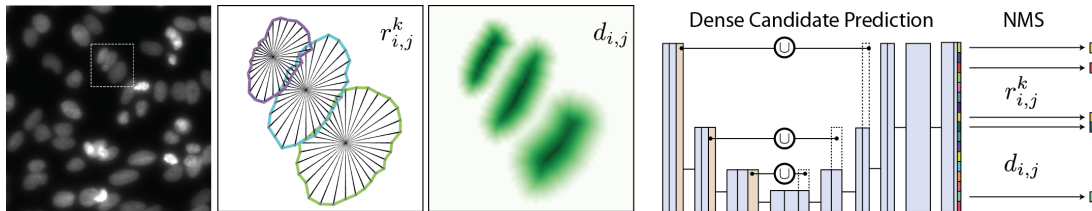
- goal: accurate spatial prediction

Labels



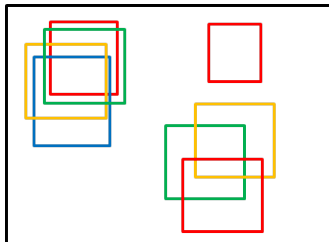
- adding uncertainty = reliable and robust prediction

Instance Segmentation Tooling: StarDist



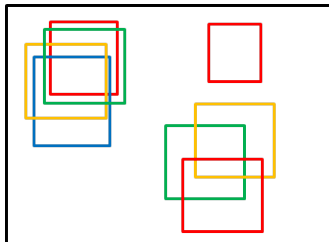
Obtaining Uncertainties for StarDist (Siddiqui *et al.*, 2023)

ensemble predictions
provide multitude of labels

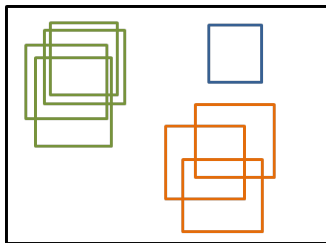


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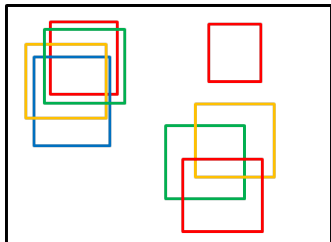


clustering for
homogenous instance
labels

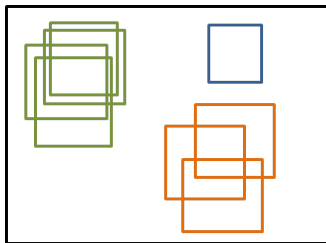


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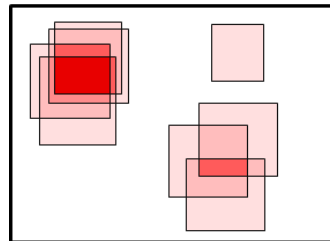
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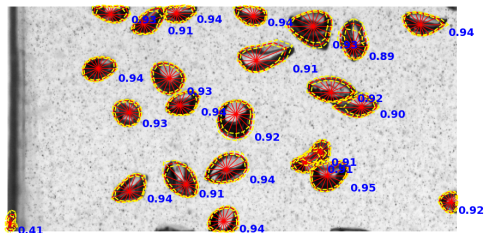
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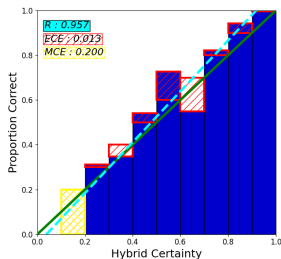
calibrated **certainty scores** by region of most overlap



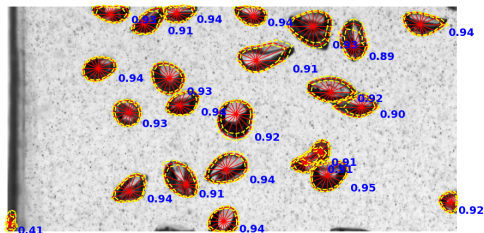
Informed Predictions with Uncertainties and Calibration Plots



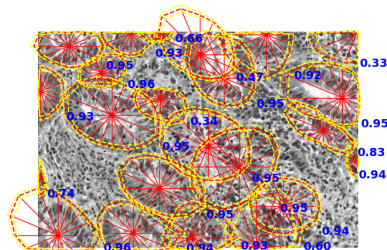
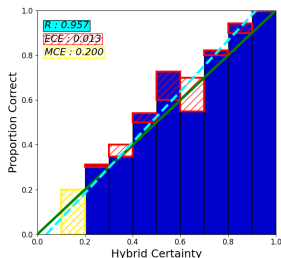
benign segmentation
(bubble segmentation)



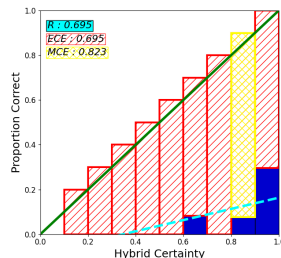
Informed Predictions with Uncertainties and Calibration Plots



benign segmentation
(bubble segmentation)



malignant segmentation
(gland tumor cell segmentation)



Summary

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Thank you for your attention!

Looking forward to questions, feedback and comments.

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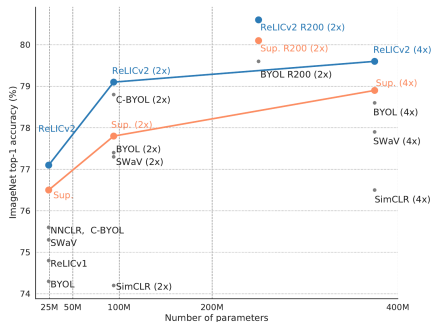
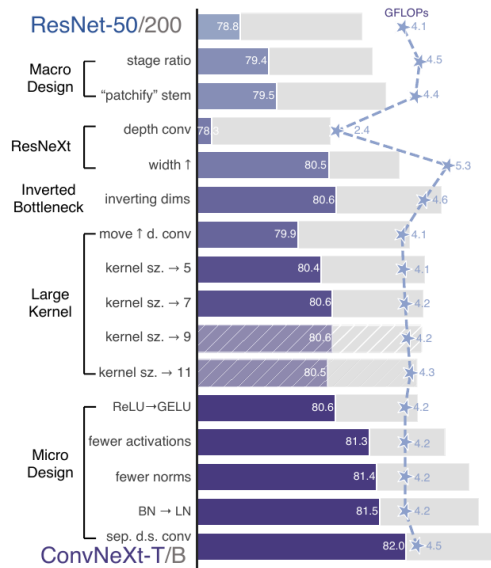
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Appendix

Derived Uncertainties

State-of-the-Art, SOTA



from Tomasev *et al.* (2022)

■ SOTA = (uncertified) reference to check for progress

■ accuracy often a central figure of merit

■ diff. quantification in machine learning

A classification SOTA for demonstration

image classification on imagenette ([Howard et al., 2022](#))



...

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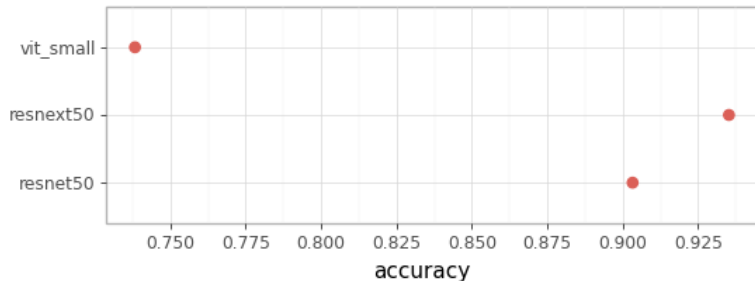


Figure 1 (a):
Accuracy estimates
on 10-class image
classification for
three different ML
architectures. Taken

from ([Steinbach et al., 2022](#))

Accuracies with Uncertainties from Cross-Validation

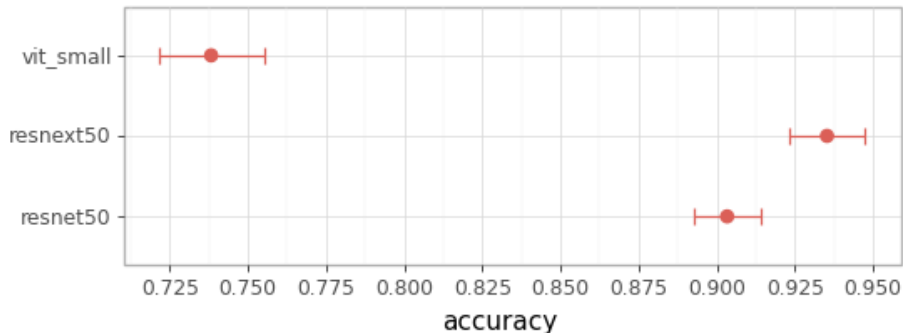


Figure 1 (b): Accuracy estimates on 10-class image classification for three different ML architectures. Point estimates and confidence intervals obtained from 20-fold cross validation is shown. Taken from (Steinbach *et al.*, 2022)

Approximated Uncertainties $\hat{\sigma}$

Approximate Accuracy as a Bernoulli probability

$$\mu_{\text{ACC}} \pm \hat{\sigma}_{\text{ACC}} = \mu_{\text{ACC}} \pm z \sqrt{\frac{1}{n_{\text{holdout}}} \text{ACC}_{\text{holdout}} (1 - \text{ACC}_{\text{holdout}})}$$

In the limit of large numbers, this converges to a normal distribution. Use z to construct confidence interval assuming normality.

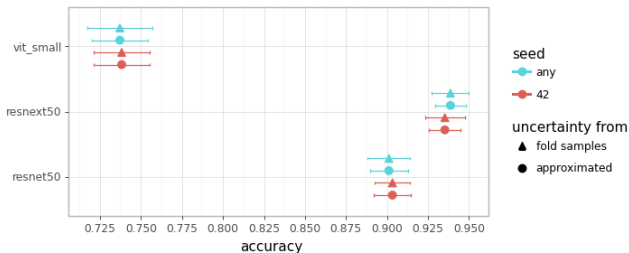
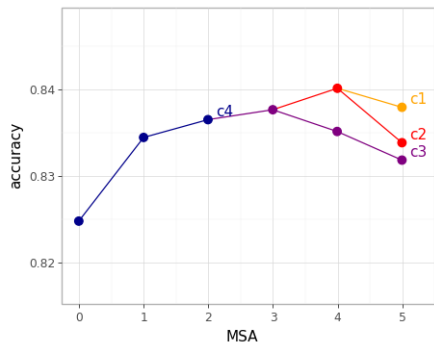


Figure 5: Comparison of fold sample based uncertainty with approximated uncertainty using eq. (1) (Raschka, 2018). Each estimate was obtained for one seed (42) or any seed available (total 6 seeds). The uncertainty plotted for seed 42 was obtained using the approximation in eq. (1). The uncertainty plotted for all seeds was obtained using the sample standard deviation. Taken from (Steinbach et al., 2022)

How Do Vision Transformers Work? (Park & Kim, 2022)



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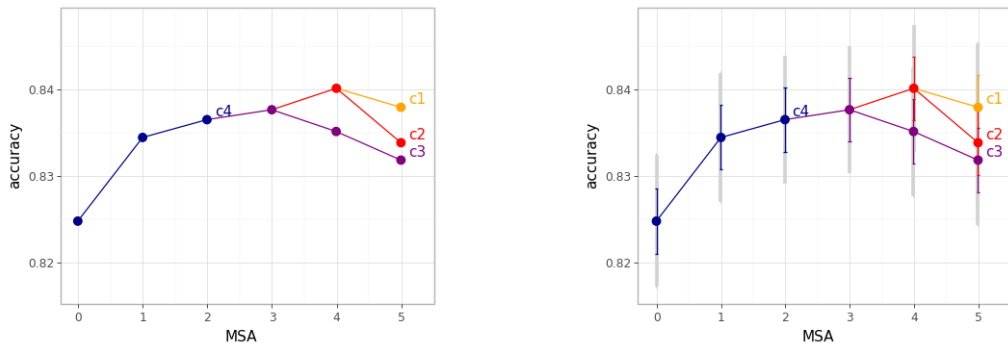


Figure 2: Reproduction of figure 12a from Park & Kim (2022) (left). Augmentation of the same figure with estimated accuracy calculated using eq. (1) using a one-sigma 68.2% (colored) and two-sigma 95% (grey) confidence interval (right). Data to reproduce these figures was obtained by using Rohatgi (2021) on the figures from the preprint PDF. Taken from

(Steinbach et al., 2022)

More Sources of Variance

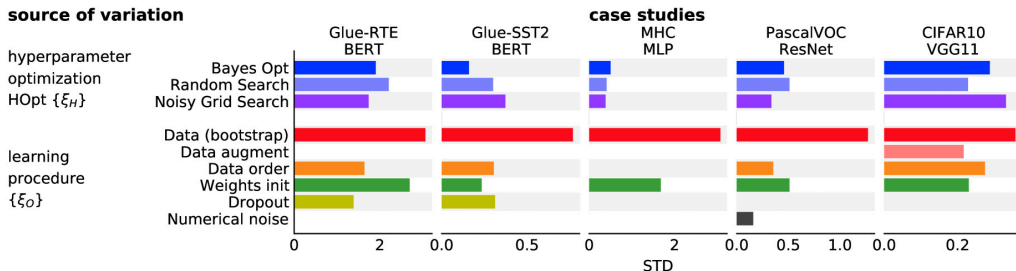


Figure 1 of (Bouthillier *et al.*, 2021): Different sources of variation of the measured performance: across our different case studies, as a fraction of the variance induced by bootstrapping the data. For hyperparameter optimization, we studied several algorithms.

Takeaways: Let's “increase the quality of evidence”¹

- **uncertainties are essential**

(strong hint for communicating and reviewing academic results)

¹G. Varoquaux at ICLR's ML Eval workshop 2022

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